

Seat	
No.	

M.Sc. (Part – I) (Semester – I) Examination, 2015 ELECTRONICS (New)

Paper - I: Numerical Methods

Day and Date: Wednesday, 15-4-2015 Max. Marks: 70

Time: 11.00 a.m. to 2.00 p.m.

Instructions: 1) Attempt five questions.

2) Question 1 and 2 are compulsory.

3) Attempt any three from Q. 3 to Q. 7.

4) Figures to the right indicate full marks.

1. A) Choose correct alternative:

8

1) The error appeared due to truncation of the higher order terms is called

a) Truncation error

b) Absolute error

c) Round-off error

d) Relative error

2) For solution of system of linear equation the coefficient matrix must be

a) Singular

b) Non-singular

c) Sparse

d) Primitive

3) In Gaussian elimination method, the coefficient matrix is reduced to _____ matrix.

a) Identity

b) Lower triangular

c) Diagonal

d) All of these

4) Laplace transformation of sin ω t is given by F(s) =

a)
$$\frac{\omega}{s^2 + \omega^2}$$

b)
$$\frac{s}{s^2 + \omega^2}$$

c)
$$\frac{s^2}{\omega^2}$$

d)
$$\frac{\omega^2}{s^2}$$



5	If a set of n	points is available.	then nth order forw	ard difference is
v,	in a oct of fi	politio io avaliabio,	ulcilli olacilolw	ara annoronoc io

a) zero

b) infinity

c) 10

d) none of these

a) Trapezoidal

b) Simpson $\frac{1}{3}$

c) Simpson $\frac{3}{8}$

d) Lagrangian

a) $O(h^2)$

b) O(h³)

c) $O(h^1)$

d) $O(h^4)$

- a) Initial value problem
- b) Final value problem
- c) Boundary value problem
- d) None of these

B) State true or false:

6

- 1) Least squares fitting process of straight line gives empirical relation of the type $y = ax^2 + bx + c$.
- 2) R 2R ladder network gives system of linear equations of tridiagonal coefficient matrix.

3) Laplace transformation of
$$f(t) = f^n$$
 is given by $F(s) = \frac{n!}{s^{n+1}}$.

5) R – K method gives solution to the system of linear equation.

6)
$$\Delta^2 + 0 = (E - 1)^2 y0$$
.

2. A) Attempt any two of following:

10

- 1) What do you mean by forward substitution and backward substitution?
- 2) Find f'(x) at x = 4 following is the set of points.

x 0 2 4 6

f(x) 0 4 16 36 64

- 3) Write a note on inverse of matrix.
- B) Write a note on Laplace Inverse Transformation.

4

3. A) Describe formulation of system of linear equations. Solve by using Gauss Jordan method.

8

8

$$2x_1 - 6x_2 + 8x_3 = 24$$

$$5x_1 + 4x_2 - 3x_3 = 2$$

$$3x_1 + x_2 + 2x_3 = 16$$

B) Write a note on LV factorization.

6

8

4. A) Describe in detail least-squares fitting process for curve fitting. Fit the following data to straight line.

x 2 4 6 8 10

y 1.6 3.6 7.9 17.4 38.6

B) With suitable example describe Newton's backward difference interpolation. 6

5. A) What do you mean by Laplace Transformation? Discuss the transient response of RC circuit.

8

B) Derive the expression for Laplace Transformation of differentiation of function.

50

. 6

6. A) Derive the expression first order and second order derivative of given interpolating polynomial.

8

B) Find Y(25) by using Newton's forward diff. method.

x 10

20

30

40

y 9.21 17.54 31.82 55.32 92.51

6

7. A) Describe Runge-Kutta method for solution of ordinary differential equation.

8

B) Evaluate
$$= \int_0^1 \frac{1}{1+x} dx$$
.

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Seat	
No.	

		ELECTRONIC	CS (New) entation Design	
-	oate : Friday, 17-4- 00 a.m. to 2.00 p.r			Max. Marks : 70
Ir	n structions : 1) G 2) S 3) F	olve any three Q.	ompulsory. . out of Q. 3 to Q. 7 indicate full marks	7. 3.
1. A) Ch	oose correct alter	native :		8
1)	The is o			
			c) hysteresis	
2)	thermistor.			or compared with
			c) more, more	
3)	•		n relation to ambie	
40	•		c) differential	•
4)	The output voltag	e of the four eleme	ent variable bridge	İS
	a) $\frac{Vin}{4}X$	b) $\frac{\text{Vin}}{2}X$	c) Vin x	d) Vin 4x
5)	a) General purposb) FET input and	se	amplifier are the mo	ost relevant.
6)			mission the full sca c) 16 mA	
7)	The co change in input signal ratiometric	gnal.	re useful to measu c) precision	rement of fractional d) none of these
8)	The ZB30 is a) isolation ampli c) signal condition		b) power supply d) programmable	e amplifier

SLR-SP - 229



	B)	State true or false .	6
		1) The digital ground lines are usually quite noisy and have large current spike.	
		2) The LED is based on the principle of transmission of photon.	
		3) The AD 590 and LM 35 has provide the output signal of same type.	
		4) The copper amplifier can be electronic or mechanical.	
		5) The semiconductor strain gauge has more output than metal strain gauge.	
		6) The error and accuracy are expressed in percentage.	
2.	A)	Attempt any two:	10
		1) Discuss the static and dynamic characteristics.	
		2) Write a note on excitation.	
		3) Explain isolation amplifier model 289.	
	B)	Explain 4 to 20 mA current transmission.	4
3.	A)	Explain the need of DAS. Explain multi-channel DAS.	9
	B)	Write a note on AD 524.	5
4.	A)	Explain in detail general block diagram of instrument design for measurement.	9
	B)	Write a note on IR proximity sensor.	5
5.	A)	Explain the simple interfacing circuit for PT 100 and AD 590.	9
	B)	Write a note on strain gauge.	5
6.	A)	Explain in detail I to V and V to I convertor.	9
	B)	Write a note on compact data loggers.	5
7.	A)	Explain in detail AC and DC signal conditioning system.	9
	B)	Write a note on electromagnetic and electrostatic shielding.	5



Seat	
No.	

M.Sc. (Part – I) (Semester – I) Examination, 2015 ELECTRONICS (New)

Paper – III : Po	wer Electronics
Day and Date : Monday, 20-4-2015	Total Marks : 70
Time: 11.00 a.m. to 2.00 p.m.	
Instructions: 1) Answer five questions. 2) Q. No. 1 and 2 are com 3) Attempt any three from 4) Figures to the right indi	Q. No. 3 to Q. No. 7 .
1. A) Choose the correct answer.	8
 In three phase unidirectional control remaining one is 	oller when two phase voltage are positive,
a) Positive	b) Negative
c) Zero	d) None
 2) AC voltage controllers are used in a) AC magnet control b) Lighting control c) Speed control of induction model d) All of these 	
Single quadrant converter is also	called
a) Semiconverter	b) Dual converter
c) Half converter	d) Full converter
4) In voltage source inverter the out	put ac voltage depends on
a) Input ac voltage	b) Input dc voltage
c) Both (a) and (b)	d) None of these
5) The chopper convertsDo	C voltage into DC volt.
a) Fixed, variable	b) Variable, fixed
c) Fixed, fixed	d) Variable, variable
	PTO



		6)	is also called self comm	utated inverter.	
			a) Parallel inverter	b) Series inverter	
			c) Bridge inverter	d) Both (a) and (b)	
		7)	Single phase half wave controller is	also called as	
			a) Bi-directional controller	b) Uni-directional controller	
			c) Single quadrant controller	d) None of these	
		8)	In three phase controller when three equal to input phase voltage.	e devices are conducting, is	
			a) Output phase voltage	b) Output phase current	
			c) Input current	d) None	
	B)	Sta	ate true or false .		6
		1)	Integral cycle control can be advised and limited range control.	l only for loads with high time constant	
		2)		rd harmonics from the output voltage verter is to use single pulse modulation.	
		3)	In three phase voltages V_a , V_b , V_c from each other by 120°.	nave similar waveforms but displaced	
		4)	A chopper, where voltage as well as type-A chopper.	s current remain negative is known as	
		5)	In dc choppers the waveform for L continuous.	/P and O/P voltage are respectively	
		6)	In AC on-off voltage controller the p	ower factor is equal to \sqrt{K} .	
2.	A)	Att	tempt any two .		10
		1)	Write a note on clacc-D-chopper.		
		2)	Give the comparison between 180 bridge inverter.	° mode and 120° mode three phase	
		3)	What do you mean by dual converte	er?	
	B)	Ex	plain the need of free-wheeling diode).	4
Q	Δ١	F۷	nlain the principle of eten-down chapp	er with resistive load. Derive necessary	
J.	~)		ations.	Ci with resistive load. Delive necessary	8
	B۱		nat are chopper control strategies?		6
	-,		o onoppor oonin or on atogroo		•



4.	A)	Explain principle of ON-OFF controller in detail and derive the equation for output voltage.	8
	B)	What is inverter? Explain operation of single phase bridge inverter.	6
5.	A)	Explain single phase AC bidirectional voltage controller with resistive load and derive the relation for output voltage.	8
	B)	Discuss three phase to single phase cycloconverter.	6
6.	A)	Describe the operation of fully controlled bridge rectifier with R-L load with necessary waveforms.	8
	B)	Explain symmetrical angle control technique used for power factor improvement of single phase converter.	6
7.	A)	Explain three phase half wave controlled rectifier. Draw necessary waveform and derive it.	8
	B)	Discuss the effect of duty cycle on phase control.	6



Seat	
No.	

M.Sc – I (Semester – I) Examination, 2015 ELECTRONICS (New)

	Paper	- IV : Advance	ed Microcontrolle	ers	
Day and [Date : Wednesday	ı, 22-4-2015		Max. Marks :	70
Time: 11.	.00 a.m. to 2.00 p	.m.			
Instr	uctions: 1) Q. N	lo. 1 and Q. No. 2	are compulsory .		
	2) Solv	ve any three from	Q. No. 3 to Q. No. 7 .		
	3) Figu	ires to the right in	dicate full marks.		
	4) Dra	w necessary diagi	ram and label them.		
1. A) Cł	noose correct alte	ernative.			8
1)	Clearing a TRIS	x bit will make tha	t perticular PIN as		
·	a) Output		b) Input		
	c) Input and Ou	tput	d) Stop		
2)	BRGH bit of Tra		Control Register (T)	KSTA) kept as 1 to	
	a) high		b) low		
	c) medium		d) none of the	ese	
3)	Select different	register from the fo	ollowing		
	a) R0	b) R1	c) R2	d) R3	
4)	Program memor	y address 0000H l	known as	vector.	
	a) Interrupt		b) Sleep mod	e	
	c) Reset		d) Both a) an	d c)	
5)		_ is arithmetic inst	ruction.		
	a) SLEEP		b) NOP		
	c) RETFIE		d) INCFSZ		
6)		_ register is used to	o enable and disable	individual external	
	interrupts.		,		
	a) GIMSK	b) GISK	c) SREG	d) MCUCR	

SLR-SP – 231

		7)	PIC has	address	ing mod	es.		
			a) 4	b) 6	c)	7	d) 2	
		8)		_bit used to select	t two me	mory banks at e	ach time in PIC	
			microcontroller.					
			a) IRP	b) RPI	c)	both a) and b)	d) none of the	se
	B)	Sta	ate true or false .					6
		1)	SEC instruction of	dosent affect carr	y flag.			
		2)	IRP is used to se	lect register bank	in PIC	micro controller		
		3)	AVR microcontro	ller has 8 channe	l 8 bit Al	DC.		
		4)	PORTA of PIC is	8 bit Bi-direction	al I/O po	ort.		
		5)	The power on rebelow a certain th		tes whe	n the power su	pply voltage is	
		6)	RS pin of LCD is	cleared to send co	ommano	d and set for sen	d data on LCD.	
2.	A)	So	olve any two :					10
	,		Write note on Ari	thmatic instruction	ns of AV	/R.		
		2)	Explain in detail p	oorts of PIC micro	controll	er.		
			Write note on me					
	B)	Wr	rite features of AV	R microcontroller	'in detai	il.		4
3.	A)	Wr	rite program to tog	gle LED connecte	ed to PC	PRTA.		8
	-		rite note on interru					6
4	Δ)	Co	onfigure on-chip A	DC of PIC to conv	vert anal	og innut into dig	ital connected	
•	, ,,		channel 0.		ortanai	og inparimo aig	na com cotoa	10
	B)	Ex	plain clock and re	eset circuit of AVF	₹.			4
5.	A)	Wr	rite note on times	of AVR controller				10
	B)	Ex	plain Relay Interfa	acing to the AVR.				4
6.	A)	Ex	plain architecture	of PIC microcont	roller.			8
	B)	Wr	rite note on compa	are capture mode.	•			6
7.	A)	Ex	plain watchdog tir	nes of AVR.				7
	B)	Ex	plain addressing ı	modes of PIC mic	rocontro	oller.		7

Seat	
Seal	
No.	
140.	

M.Sc. (Part – I) (Semester – I) Examination, 2015 ELECTRONICS (Old)

	Paper – I : Mathem	natical Technique	es
Day and Date: Wedn Time: 11.00 a.m. to	• •		Total Marks : 70
Instructions	: 1) Attempt five questi 2) Question 1 and 2 a 3) Attempt any three 4) Figures to the righ	re compulsory . from Q. 3 to Q. 7 .	5.
1. A) Select correc	t alternatives :		8
1) Laplace tra	ansformation of $\frac{di(t)}{dt}$ is		
a) $\frac{I(s)}{s}$	b) sl(s)	
c) $\frac{I(s)}{1-\alpha}$	d) $(1-\alpha)$ ls	
2) The secon	d order forward differenc	$e \Delta^2 y_0$ can be expre	essed as
a) $(E-1)^2$		$(E^2-1)y_0$	
c) $\frac{E^2}{y_0}$	d	$) E^2 - y_0$	
3) Fourier sei	ries expansion, the functi	ion should satisfy	condition.
a) Newtor	n b) Euler	
c) Dirichle	•) Gauss	
•	dder Network results into		natrix.
a) L-matri) U-matrix	
c) Tri diag	gonal matrix d) All of these	



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,	5)	For numerical integration by S considered.	imp	oson ¹ / ₃ rule	points are	
		a) 2	b)	3		
		c) 4	d)	None of these		
(6)	Determination of solution of ordproblem.	lina	ry differential equation at a	$x = x_0$ is the	
		a) Initial value	b)	Final value		
		c) Boundary	d)	None of these		
	7)	In Newton's forward difference the	e n ^t	ⁿ order difference is always _	· · · · · · · · · · · · · · · · · · ·	
		a) 1	b)	∞		
		c) 0	d)	All of these		
	8)	The function is said to be even s	syn	nmetric if f(– t) =	·	
		a) f(t)	b)	- f(t)		
		c) $f(-t)$	d)	None of these		
B) 3	Sta	ate true or false :				6
	1)	The Fourier coefficient q ₀ repres	ser	ts maximum value the fund	ction.	
;	2)	Laplace transformation of unit for	unc	tion is ¹ / _s .		
;	3)	For square matrix if $ A \neq 0$, the	en	t is said to be singular ma	trix.	
	4)	Lagrangian interpolating polyno	mia	al is for equally spaced data	a points.	
	5)	For solution of ordinary differenti	al e	equation R – K method can	be adopted.	
(6)	Each splines in cubic splines ca	n b	e expressed by third order	polynomial.	
A) ,	An	swer any two of following:				10

- 2. A) Answer any two of following:
 - 1) Describe Gaussian elimination method.
 - 2) Write a note on least squares fitting process.
 - 3) Evaluate $I = \int_{1}^{2} x \, dx$.
 - B) What do you mean by Initial value and boundary value problem.

8

6

8

- 3. A) Using Newton-cotes quadrature formula derive expression for Simpson's $^1\!/_3$ rule of numerical integration.
 - B) Using Simpson $\frac{1}{3}$ rule evaluate $I = \int_{0}^{1} \frac{dx}{1+x}$.
- 4. A) Obtain Laplace transformation of differentiation of function.
 - B) Using Laplace transformation describe the response of RC circuit for DC input.
- 5. A) What do you mean by interpolation? Describe Newton's forward difference interpolation technique.
 - B) Find y(0.3) for following data points.
 - **x**: 0 0.2 0.4 0.6 0.8 1.0
 - y: 1.0 0.808 0.664 0.616 0.712 1.0
- 6. A) Derive the expression for Fourier coefficient.
 - B) Derive Fourier series expansion for half wave rectifier wave.
- 7. A) With suitable example describe Gauss-Jordan elimination method for solution of system of equation.
 - B) Solve by Gaussian elimination method.

$$x_1 + x_2 - x_3 = -3$$

$$6x_1 + 2x_2 + 2x_3 = 2$$

$$-3x_1 + x_2 + x_3 = 5$$



Seat	
No.	

M.Sc. (Part – I) (Semester – I) Examination, 2015 ELECTRONICS (Old)

	Paper	ELECTRONIC - II : Instrume	CS (Old) entation Desig	n	
-	Date : Friday, 17-4-20 1.00 a.m. to 2.00 p.m.)15		Total Marks : 7	0
In	estructions: 1) Q. 1 a 2) Atte		npulsory. ions from Q. 3 to	Q. 7 .	
1. A) C	Choose correct alterna	tives of the follow	wing :		8
1)	Self generating trans	sducers are	transduc	ers.	
	a) active	b) passive	c) secondary	d) inverse	
2)	Quartz and Rochelle	salt belongs to	of Pi	ezo-electric material.	
			b) Synthetic gro		
	c) Fiber group		d) None of these	e	
3)) LVDT is a/an	transdu	cer.		
	a) Magneto-strict is	on	b) Inductive		
	c) Resistive		d) Eddy current		
4)	Capacitive transduce measurement.	ers are normally o	employed for		
	a) static	b) dynamic	c) transient	d) both a) and b)	
5))i	s example of pho	oto emissive cell.		
	a) LDR		b) Photo diode		
	c) Photo multiplier		d) None of these	e	
6)	Photo conductive ce	ell consists of a th	nin film of		
	a) Quartz	b) Lithium	c) Selenium	d) None of these	
7)	For conversion of an	alog signal into d	digital,	are used.	
	a) DAC		b) ADC		
	c) Both a) and b)		d) None of these	e	
8))i	s active temperat	ture sensor.		
	a) Tachometer	b) LM 35	c) PT 100	d) Thermocouple	

SLR-SP-233



	-,	State True or False :	6
		1) Wheatstone Bridge is DC Bridge.	
		2) A to D convertor use to measure and record.	
		3) AD524 is programmable instrumentation amplifier.	
		4) Strain gauge use to measure pressure.	
		5) SYHS230 is humidity sensor.	
		6) Relays are use to reduce noise.	
2.	A)	Solve any two of the following:	10
		1) Explain IR proximity sensor.	
		2) Write note on single channel data acquisition system.	
		3) Explain stain-gauge in detail.	
	B)	What are Recorders ? Explain in short.	4
3.	A)	Compare data acquisition system and the data logger.	8
	B)	Explain F to V convertor in detail.	6
4.	A)	Design instrumentation for measurement of temperature.	10
	B)	Explain I to V convertor in detail.	4
5.	A)	Explain Micro-controller based minimum system for data acquisition.	10
	B)	Write note on plotters.	4
6.	A)	General block diagram of instrument design for measurement, explain in detail.	10
	B)	Explain characteristics of sensors.	4
7.	A)	Write note on Grounding, Electromagnetic and electrostatic shielding.	8
	B)	Write note on Actuators.	6



Seat	
No.	

M.Sc. (Part - I) (Semester - I) Examination, 2015 ELECTRONICS (Old) IV : Advanced Microsoft

	Paper	– IV : A	Advanced	Microcontrolle	ers	
-	ate : Wednesday, 0 a.m. to 2.00 p.		15		Total Mark	ks : 70
Instr	3) At	ıestion 1 tempt an	and 2 are co ny three fron	ompulsory. n Q. 3 to Q. 7 . licate full marks.		
1. a) Cho	oose correct ans	wer:				8
1)	With reference t	o Embed	ded system	s, POR stands fo	or	
	A) Power-of-RC	M		B) Power-of-RA	ΔM	
	C) Power-on-Re	eset		D) Program-on-	ROM	
2)	LCD module do	es not ha	ve following	pin		
	A) EN	B) R	S	C) R/W	D) EOC	
3)	PIC 16F877 has		pins.			
	A) 28	B) 4	0	C) 32	D) 40	
4)	The program me	emory ca	pacity of PIC	C 16F877 is	KB.	
	A) 10	B) 8		C) 14	D) 16	
5)	There are		general purp	ose registers in A	ATMega8.	
	A) 8	B) 10	6	C) 24	D) 32	
6)	On-chip RAM siz	ze in ATN	Mega8 is			
	A) 64 Bytes	B) 1	28 Bytes	C) 512 Bytes	D) 1024 Bytes	
7)	Single word inst	ructions i	in PIC 16F87	77 are		
	A) 10	B) 2	0	C) 35	D) 40	
8)	There are		powerful ins	tructions in ATM	ega8.	
	A) 72	B) 1	80	C) 130	D) 132	

SLR-SP - 235



	b)	State true or false :	6
		1) PWM is related to duty cycle of pulse.	
		2) OLED consumes more power as compare to LED.	
		3) Data transfer is in serial form over I ² C Bus.	
		4) Timers in microcontroller counts external pulses.	
		5) AVR has on-chip flash memory.	
		6) Matrix type keyboard saves I/O lines.	
2.	A)	Attempt two :	10
		a) Explain status register of PIC 16F877.	
		b) Enlist the features of AVR series microcontrollers.	
		c) State the advantages and applications of I ² C devices.	
	B)	Explain the need of opto coupler in interfacing.	4
3.	a)	Explain the architecture of PIC 16F877.	8
	b)	Explain interfacing of smart LCD module with AVR.	6
4.	a)	Explain memory structure of PIC 16F877.	8
	b)	What are the advantages of bit oriented instructions? Explain any five bit oriented instructions of AVR.	6
5.	a)	What do you mean by an interrupt ? Explain how interrupts are processed by AVR microcontrollers.	8
	b)	Explain the procedure of developing project using MPLAB.	6
6.	a)	Explain memory addressing modes of AVR with the help of examples.	8
	b)	Explain the step by step procedure to install MPLAB on desktop computers.	6
7.	a)	Explain conditional branching instruments of AVR microcontroller with examples.	8
	b)	What is stack? Explain any five stack related instructions of AVR.	6



Seat	
No.	

M.Sc. - I (Semester - II) Examination, 2015

ELECTRONICS (New) Paper – V : Control Theory	
Day and Date: Thursday, 16-4-2015 Time: 11.00 a.m. to 2.00 p.m.	arks : 70
Instructions: 1) Answerfive questions.	
2) Question 1 and 2 are compulsory.	
3) Attempt any three from Q. 3 to Q. 7.	
4) Figures to the right indicate full marks.	
1. a) Choose correct answer:	8
1) Laplace transform of 1 is	
a) $\frac{1}{s}$ b) s c) $\frac{s}{s+1}$ d) none of the	ese
2) is graphical representation of transfer function.	
a) Node b) Loop c) Path d) Block diag	ram
3) For type one system, the steady state acceleration error is	
a) 0 b) 1 c) $\frac{1}{Ka}$ d) none of the	ese
4) Which of the following technique gives quick transient and stability respon	se?
a) Nyquist b) Root locus c) Bode d) Polar	
5) Feedback system has advantage of transient response).
a) Improving b) Decreasing c) Both a and b d) none of the	ese P.T.O.



		6)		-					-			positive		-	or if the	ese	
			a)	stabl	е		b)	unstab	ole	c)	both a	and b	d)	none	of the	se	
		7)			-	the t first a		-	ed for th	he r	espons	e to rea	ich _	-	of	the	
			a)	60%			b)	70%		c)	50%		d)	40%			
		8)				is und	dam	ped na	tural fro	equ	ency.						
			a)	ζ			b)	ω_{c}		c)	ω_{n}		d)	f			
	b)	1) 2) 3) 4) 5)	Tate true or false : A high damping ratio will be a high overshoot. Bode plote is a time domain test. Nyquist criteria gives direct value of corner frequency. The Bode plot is applicable to minimum phase network. Open loop system is most sensitive to the presence of non linearities. Feedback system has advantage of reduce sensitivity.									6					
2.	ŕ	1) 2) 3) Ex	Ex Ex Wr plai	Explain comparison between open loop and close loop system. Explain roll of controllers in process industry. Write note on polar plots. plain discontinuous (ON-OFF) control action with their performance and aracteristics.							10						
3.	,		•			d test on be	•		e and fr	equ	uency re	esponse	Э.				8 6
4.	•		•					cus con e feedb	•								8 6
5.	,		•					se of se nsporta			er syste	m.					8 6
6.			-		-	of se ot cor	-	_	ınd mo	dula	ating co	ontroller	S				8 6
7.			-				-	of stab action.	-								8



Seat	
No.	

M.Sc. (Part – I) (Semester – II) (New) Examination, 2015 ELECTRONICS Paper – VI : Real Time Operating System

	•			
Day and Da	ate : Saturday, 1	8-4-2015		Max.Marks : 70
Time: 11.0	0 a.m. to 2.00 բ	o.m.		
Instruc	ctions: 1) Ans	swer five questio	ns.	
	2) Que	estion 1 and 2 are	e compulsory.	
	3) Atte	empt any three f	rom Q. 3 to Q. 7 .	
	4) Figu	ures to the right	indicate full marks.	
1. A) Cho	ose correct alt	ernatives :		8
,			_ for the task for exec	cution.
ć	a) Protection	b) Lock	c) Permission	d) Prohibition
2) _			tal characteristics of t	
ć	a) Stack size		b) Time schedul	e
(c) Priority		d) Context	
3) 7	To avoid starva	tion	task is executed.	
ć	a) Semaphore		b) Idle	
(c) Ideal		d) Event	
	f two tasks sha may occurs.	re the resources	commonly, then	situation
á	a) Spinlock		b) Livelock	
(c) Deadlock		d) Race condition	on
5) 7	•	de is always exc volt.	cited with the constar	nt voltage source of
á	a) 220 mV		b) 5 V	
(c) 420 mV		d) 100 mV	
			•	

SLR-SP-	· 237 -2	2-	
6)	Hard real time system is		
	a) Reversible	b) Irreversible	
	c) Ideal	d) None of these	
7)	The Kernel of the RTOS should p	provide	_ to the task.
	a) Memory management	b) Resource man	agement
	c) Time management	d) All of these	
8)	For context switching	object is operatin	g.
	a) Dispatcher	b) Queue	
	c) Event register	d) Mutex	
B) St	ate True or False :		6
1)	During pre-empitive scheduling pre-empited.	g the task of highest	priority is always
2)	For intertask communication the	queue is acts as first-i	n first-out memory.
3)	The task is an example of endles	ss loop.	
4)	RTLinux Kernel is superimposition	on of the real time Kern	el on Linux Kernel.
5)	For context switching heap mem	nory portion is used.	
6)	The mutex is not an object of the	e Kernel.	
2. A) At	tempt any two :		10
1)	Write a note of FSM of the task.		
2)	Describe in detail the Round-Ro	bin scheduling mecha	nism.
3)	With suitable example describe	the hard and soft real	time systems.
B) W	hat do you mean by context switc	hing.	4



3.	A)	With suitable block diagram describe a designing of an embedded system for measurement of humidity. Use AVR ATmega 8 L microcontroller.	7
	B)	What is RTOS? Describe characteristics of RTOS.	7
4.	A)	With suitable diagram explain priority based pre-empitive scheduling mechanism.	7
	B)	What do you mean by priority inversion?	7
5.	A)	Describe in detail the architecture of the Kernel of RTLinux.	7
	B)	What do you mean by semaphore?	7
6.	A)	Describe the structure of RTOS Kernel. Explain the scheduling mechanism.	7
	B)	Describe use of message box for intertask communication.	7
7.	A)	Describe the architecture of the RTOS Kernel micro C/OS – II.	7
	B)	Write in program in any RTOS to Read/Write IO ports of any micro controller.	
			7

SLR-SP - 238



Seat	
No.	

M.Sc. (Part – I) (Semester – II) (New) Examination, 2015 ELECTRONICS Optoelectronics (Paper – VII)

Day and E	Date : Tuesday, 21	-4-2015				To	otal. Marks	: 70
Time : 11.	00 a.m. to 2.00 p.	m.						
Ins	3) Fig	nestions 1 and 2 Note any three fr Gures to the righ I questions carry	rom ht in	Q. 3 to	Q. 7 . full mari	ks.		
1. A) Ch	noose correct alter	natives :						8
1)	Optical fiber work	s with the						
	a) Snell's law		b)	Total in	nternal re	eflection		
	c) Variation in RI		d)	All of the	nese			
2)	In P-N junction p upon the doping of	hoto diode				oletion laye	r depends	
	a) length	b) hight	c)	width		d) none o	f these	
3)	the electrical field	_	n re	fractive	e index li	nearly prop	oortional to	
	a) Pockets effect	t	b)	Kerr's	effect			
	c) Faraday effec	t	d)	None o	of these			
4)	A quarterwave pla	ate rotates the pla	ane	of pola	rization b	у	degree.	
	a) 180	b) 90	c)	270		d) 360		
5)	For high speed op	otical network		is	the bes	t suitable liç	ght source.	
	a) Surface emitti	ng LED	b)	Edge e	emitting L	_ED		
	c) Fabry Perrot L	.ED	d)	DFBLD)			



		6)	Silica fiber h	as highe	st data	rate at $_$		wave	elengt	h.		
			a) 850 nm	b)	1300 n	m c)	1400 r	nm	d) 1	550 nm		
		7)	Avalanche F	Photo dio	de cons	umes _		_power.				
			a) low	b)	high	c)	zero		d) a	II of these		
		8)	In optical fib	er materi	al dispe	ersion ca	auses_		of t	he pulse.		
			a) Distortio	n		b)	Attenu	ation				
			c) Broadeni	ing		d)	Narrov	wing				
	B)	1) 2) 3) 4) 5)	ate true or fa In birefringe Kerr effect of In single monotore. A loss of Octoorel determined to the core of the core. He-Ne lase	ence crys demonstr ode grade dBm powe ectors cor	ates ele ed index er is eq nverts c	ectro-op k fiber th uivalent optical si	tic effect e RI of with th gnal int	ct. core is use e loss of to electric	ıniforr 10 m	mly varies w power.		6
2.	ŕ	At 1) 2) 3)	tempt any tw What do you Describe th Write a note	/o : u mean b e method e on LED	y APD ' ls of spl as optic	? icing. cal sourc	ce.					10
	D)	VV	hat do you m	ean by ni	umenca	ai aperiu	re ?					4
3.	·	bir	hat do you m refringence. escribe the co					scribe th	e phe	enomenon	of	10 4
4.	·	Н	ith suitable d e – Ne LASEI escribe the m	R source.					n and	d working o	of	10 4
5.	,		hat do you m rite a note or	-		•		ct ? Desc	ribe p	oocket cel	l.	10 4
6.	,		escribe in deta rite a note or				•	PIN diod	e as o	ptical dete	ctors.	10 4
7.			escribe in det rite a note on				s of op	tical fibe	r cabl	e.		10 4

Seat	
No.	

M.Sc. (Part – I) (Semester – II) (New) Examination, 2015 ELECTRONICS

Paper - VIII: Signals and System

	. upo	· • • • • • • • • • • • • • • • • • • •	aio aira Oyotoiii		
-	Date : Thursday, 23-4 00 a.m. to 2.00 p.m.			Total Marks : 7	70
Ins	3) Atte	stion 1 and 2 are mpt any three fr	compulsory.		
1. A) Ch	noose correct answe	ers:			8
1)	The system y(n) =	x(n) - x(n-1) is	syste	m.	
	a) dynamic		b) time invariant		
	c) linear		d) all above		
2)	An initially relaxedoutput.	system is said to	be unstable if	input produces	
	a) bounded, bound	ed	b) unbounded, un	bounded	
	c) finite, infinite		d) infinite, finite		
3)	The Fourier series terms.	s expansion of	odd periodic fund	tion contains only	
	a) constant	b) sine	c) cosine	d) variable	
4)	The unit parabolic	function is denot	ed by p(t) is		
	a) $P(t) = \frac{t^2}{2}.u(t)$		b) $P(t) = \frac{t^2}{2} . \delta(t)$		
	c) $P(t) = r(t)$		d) $P(t) = t^2$		



- 5) Convolution is used to find
 - a) The time response of LTI system
 - b) The impulse response of an LTI system
 - c) Frequency response of a system
 - d) The phase response of a LTI system
- 6) A continuous time signal x(t) is said to be symmetric signal if its satisfies the condition
 - a) x(-t) = -x(t)

b) x(-t) = x(t)

c) x(-t) = -x(2t)

- d) -x(-t) = x(-t)
- 7) The function $\frac{\sin(\pi u)}{\pi u}$ is denoted by _____ function.
 - a) Signum
- b) Sinc (u) c) Rectangular
- d) Periodic
- 8) If x(t) is odd, then its Fourier series coefficients must be
 - a) real and odd

- b) real and even
- c) imaginary and odd
- d) imaginary and even

B) State true or false:

6

- 1) The symbol\used for left division.
- 2) Energy of a power signal is finite.
- 3) The unit parabolic function can be obtained by integrating the ramp function.
- 4) The representation of signal by mathematical expression is known as signal modelling.
- 5) Folding and time delaying of a signal are commutative.
- 6) While commands allows conditional looping in which statements within the loop are executed along as the condition is true.
- 2. A) Attempt any two:

10

- a) What is MATLAB? Explain the different commands of matlab.
- b) Sketch the following signals:
 - i) u(n + 2) u(n 3)
 - ii) u(-n + 3).u(n)
- c) Define signal. Give typical examples on signals and system.
- B) Write a note on different types of file used in MATLAB.

3. A) Check whether the following system

8

- i) static/dynamic
- ii) linear/non-linear
- iii) tinvarient or not

A modulator whose carrier frequency is ω_0 giving an output $y(t) = x(t) \cos \omega_0 t$.

B) Sketch the signal $x(t) = e^{-t}$ for an interval $0 \le t \le 2$ samples the signal with sampling period T = 0.2 sec. and sketch discrete time signal.

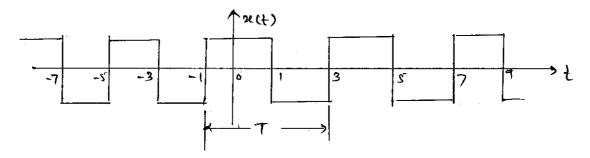
6

4. A) Obtain linear convolution of following sequence using mathematical equation method.

$$x(n) = \{1, 2, 1, 2\}$$
 and $h(n) = \{1, 1, 1\}$.

8

- B) Prove that LTI system is completely characterized by unit impulse function.
 - 6 8
- 5. A) Find the trignometric Fourier series for the periodic signal x(t) shown in figure.



- 6
- 6. A) Explain in detail about different types of operations on signals with suitable examples.
- 8

B) Sketch a discrete time signal $x(n) = 3^n$ for $-2 \le n \le 2$ and obtain

B) Explain exponential Fourier series representation.

i)
$$y(n) = \frac{x(n)}{2} + \delta(-n+2)$$

ii) y(n) = x(n).u(-2-n).

6

- 7. A) State the different properties of Fourier series and explain Parserval's theorem.
 - . 8

B) Write a note on continuous-time and discrete-time signals.

6



Seat	
No.	

M.Sc. (Part – I) (Semester – II) Examination, 2015 ELECTRONICS (Old) Paper – V : Control Theory

	•	apei – v . od	ontrol Theory		
•	Date: Thursday, 16 .00 a.m. to 2.00 p.n			Total. Marks	: 70
In	3) Att	iestion 1 and 2 a empt any three	ons. re compulsory . from Q. 3 to Q. 7 . I t indicate full mari	ks.	
1. A) Cl	hoose correct answ	er.			8
1)	Laplace Transform	m of unit step is			
	a) 1/s	b) 1	c) 1/s ²	d) 1/(s - a)	
2)	The open loop trai	nsfer function rep	oresents	system.	
	a) type – 0	b) type – I	c) type – II	d) type – III	
3)	Maximum phas	e-lead of the	compensator D	$O(s) = \frac{(0.5s + 1)}{(0.05s + 1)}, \text{ is}$	
	a) 52 deg at 4 rac	l/sec	b) 52 deg at 10	rad/sec	
	c) 55 deg at 12 ra	id/sec	d) none of the above		
4)	In the signal flow g	graph the sink no	ode has	branches.	
	a) only out going		b) only in coming		
	c) both incoming and outgoing		d) none of these		
5)	Open loop transfe integration.	r function of type	– I control system	contains	
	a) single	b) double	c) triple	d) none of these	

6) In bode plot frequency scale is



4

		a) linear	b) exponential	c) logarithmic	d) parabolic	
	7)	In second order co	ontrol system the	response is over	damped if damping	
		a) ξ < 1	b) ξ >1	c) $\xi = 1$	d) $\xi = 0$	
	8)	The control that su	ıffers from residu	al error is		
		a) PD	b) PI	c) PID	d) ON-OFF	
	B) S	tate true or false .				6
	1)	The Mass represe a mechanical body			a force is applied to place. For this the	
		relationship betwe	en M, F and x is	$F = M \frac{d^2x}{dt^2}$. Say tro	ue or false.	
	2)	Maoson's gain for	mula is used for o	defining stability of	the system.	
	3)	Transient respons during which the o				
	4)	The peak time t _p is first overshoot.	the time required	d for the response	to reach the peak of	
	5)	Polar plot is the pl	ot of frequency V	sz.		
	6)	For the unstable of response.	compensated sys	stem lead comper	sator provides fast	
2.	A) A	ttempt two (short qu	estions).			10
	a)	What are the differ	ent types of cont	rol system ? Expla	ain with advantages	

b) What is Mason's gain formula? Explain the procedure to draw signal flow

c) Write a note on 'Correlation between time and frequency response'.

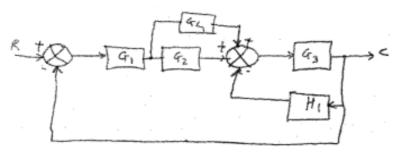
and disadvantages close loop control system.

graph from block diagram.

B) Write a note on regenerative feedback.



3. A) Reduce each diagram to single block, and determine resulting equivalent transfer function.



	B) What are the various time domain specifications?	6
4.	A) Explain Impulse response of Second order system.	8
	B) Write a note on Routh stability criterion.	6
5.	A) Explain step by step procedure to draw Bode Plot.	8
	B) Explain the term of signal flow graph.	6
6.	A) Explain the procedure to draw the root locus.	8
	B) Explain Nyquist Stability Criteria.	6
7.	A) Write a note on 'PID Controller'.	8
	B) Explain the roll of controllers in process industry.	6



Seat	
No.	

M.Sc. (Part – I) (Semester – II) Examination, 2015 ELECTRONICS (Old) Paper – VI : Real Time Operating System

Day and Date : Saturday, 18-4-2015	Total Marks:	: 70
Time: 11.00 a.m. to 2.00 p.m.		
Instructions: 1) Answer five questions 2) Questions 1 and 2 are 3) Attempt any three fro 4) Figures to the right in	compulsory. m Q. 3 to Q. 7.	
1. A) Select correct alternatives :		8
1) A task may become ready for execu	ition when it	
a) Acquire resources	b) Acquire interrupts	
c) Has highest priority	d) All of these	
The emf generated from standard p for pH range from 0 to 14.	H electrode in the range of	
a) 0 to 140 mV	b) - 420 mV to 420 mV	
c) 0 to 840 mV	d) -840 mV to 0	
On acquire the mutex counter		
a) Decrements	b) Increments	
c) Remains uncharged	d) None of these	
 The communication path established program interface routine is called 	ed between hardware and application	
a) Mutex b) Queue	c) Thread d) Pipe	
In round-robin scheduling mechanis	m the tasks are allotted with	
a) Only priority	b) Only fraction of CPU time	
 c) Both priority and CPU time 	d) None of these	
6) The RTOS Kernel micro-os-II has p	ortability	
•	b) For 8951 microcontroller only	
c) For AVR microcontroller only	d) For PIC microcontroller only	



		7) RTLinux supports to			
		a) IEEE standards b) Digi standards			
		c) Only ARM microcontrollers d) Only to VLSI devices			
		8) of the following is used for intertask communication.			
		a) Semaphore b) TCB c) SCB d) Queue			
	B)	State true or false.	6		
		1) Hardware time ticks are used to remove the task from execution state.			
		On collapsing of the deadline the soft real time system results in catastrophic change.			
		3) Static priority solves the problem of priority inversion.			
		4) Clock and reset circuits are the prime requirements of an embedded system.			
		5) Event register is not a Kernel object.			
		6) The micro c/os-II Kernel is based on rate monotonic method of scheduling.			
2.	A)	Attempt any two:	0		
	,	1) What do you mean by real time? Give the characteristics of RTOS.	•		
		2) Write a note on creation of the task.			
		3) What do you mean by static and dynamic priority?			
	B١		4		
	·		8		
3.	. A) Define the priority of the task. Describe states of the tasks in detail.				
	B)	Describe the structure of RTOS.	6		
4.	A)	Define the term scheduling. Describe with suitable example, priority based			
	,		8		
	B)	Write a note on context switching.	6		
5.	A)	What do you mean by mutex? Describe priority inversion mechanism.	8		
	B)	Describe hard and soft real time system.	6		
6.	A)	What do you mean by synchronization of task? Explain the need of semaphore to avoid the problem of deadlock.	8		
	B)	Design an embedded system to measure humidity of the environment.	6		
7.	A)	Describe micro c/os-II Kernel's features.	8		
	B)	Describe with suitable diagram the intertask communication mechanism.	6		

Seat	
No.	

M.Sc. (Part – I) (Semester – II) Examination, 2015

Pa	ELECTRONICS (Old) aper – VII : Optoelectronics	
Day and Date: Tuesday, 21-4 Time: 11.00 a.m. to 2.00 p.m		Total Marks : 70
3) Solve	er five questions. ions 1 and 2 are compulsory . any three from Q. 3 to Q. 7 . s to the right indicate full marks.	
1. A) Choose correct altern	natives:	8
1) Numerical apertur	e, NA = $\sin \theta$ =	
a) n ₁ ²	b) n ₂ ²	
c) $\left(n_1^2 - n_2^2\right)^{1/2}$	d) $(n_1 - n_2)^2$	
2) in th varies as a functio	e pulse is observed if refractive on of wavelength.	index of the material
a) Dispersion	b) Amplitude modula	ation
c) Losses	d) None of these	
3)is th	ne first order electro-optic effect.	
a) Kerr	b) Pockel	
c) Faraday	d) All of these	
4) For quarter wave p	plate the phase difference betwee	en two optical wave is
a) 90°	b) 180°	
c) 45°	d) 360°	

5) The OTDR is used to measure _____ of the optical fiber.



			a) NA	b)	Dispersion	
			c) Attenuation	d)	None of these	
		6)	For direct semiconductors the light $\boldsymbol{\lambda}$ as	e ba	and gap is related to the wavelength of	
			a) $\lambda = \frac{1}{Eg}$	b)	$\lambda = \frac{1.24}{Eg}$	
			c) $\lambda = Eg$	d)	$\lambda = 1.24 Eg$	
		7)	of the following	sho	ows linear electro-optic effect.	
			a) Glass	b)	LiNbO ₃	
			c) SnO ₂	d)	Li_2O_3	
		8)	On use of the Pointensity modulator.	cke	Phase modulator can be converted into	
			a) Polarizer	b)	Analyzer	
			c) Both a) and b)	d)	None of above	
	B)	Sta	ate True or False :			6
		1)	For graded optical fiber $n_1 > n$	2"		
		2)	Faraday effect is nothing but r	nag	neto-optic effect.	
		3)	In AO modulation, change in considered.	refr	active index due to mechanical strain is	
		4)	Photo detector, PN junction diod	e is	always connected in forward biased mode.	
		5)	Splicing is the method of mea	sur	ement of loss in optical fiber.	
		6)	Optically anisotropic crystals	exh	ibit phase modulation.	
2.	A)	Sc	lve any two from the following	:		10
		1)	Write a note on LED as optical	ıl so	ource.	
		2)	Describe pulse spread due to	ma	terial dispersion.	
		3)	Describe the methods of coup	olino	g of optical fibers.	
	B)	De	escribe in detail the AO effect.			4



3.	 A) With working principle describe mechanism of optical communication through optical fiber. 	8
	B) Write a note on numerical operature.	6
4.	A) What do you mean by birefringence? Describe electro-optic effect. Compare Pockel's and Kerr's modulators.	8
	B) Write a note on quarter wave retarding plate.	6
5.	A) What are methods of measurement of characteristic of optical fiber? Describe loss measurement method.	8
	B) Describe photo transistor as optical detectors.	6
6.	A) Describe in detail magneto-optic effect of light modulation.	8
	B) Write a note on He-Ne Laser optical source.	6
7.	A) What do you mean by step and graded index optical fibers?	8
	B) Describe APO as optical detectors.	6

SLR-SP - 243



Seat	
No.	

M.Sc. (Part – I) (Semester – II) Examination, 2015 ELECTRONICS (Old) Paper – VIII: Electronics Circuit Design

	Paper – VIII : Elect	tronics Circuit D	esign
Day and Date : Thu	rsday, 23-4-2015		Max.Marks: 70
Time: 11.00 a.m. to	o 2.00 p.m.		
Instructions:	1) Answer five question	ons.	
	2) Question 1 and 2 ar	re compulsory .	
	3) Attempt any three	from Q. 3 to Q. 7 .	
	4) Figures to the right	t indicate full marks	S.
1. A) Choose the	correct answer:		8
1) The purp	oose of the clock input	to a flip-flop is to	
a) Clear	the device		
b) Set th	ne device		
c) Alway	ys cause the output cha	ange states	
d) Contr	olling the synchronous	input	
2) IC 74121	l is		
a) Mond	stable multivibrator	b) Schmitt trig	ıger
c) Analo	og multiplexer	d) All of these)
3) The mini	mum number of flip-flo	p required in counte	er to count 60 pulses is
a) 4	b) 6	c) 8	d) 10
4) The mini	mum voltage drop acro	oss IC regulator 78X	XX/79XX series is
a) 3V	b) 2V	c) 1V	d) OV
5) IC design	n is preferred over disc	rete circuit design s	since
a) Inexp	ensive	b) More reliab	le
c) Versa	atile	d) All of these	•
,		,	5.7.0

3. A) Design a fullwave rectifier circuit with an LC filter to supply gv dc at 50 mA

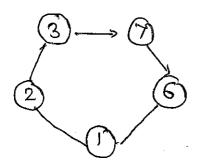
8

6

with ripple factor of 0.02.

B) Write a short note on three terminal IC regulator.

4. A) Design a counter which will be through the following sequence using JK flipflop. 8



B) Design 16: 1 mux using 4: 1 mux. 6 5. A) Explain frequency synthesizer in detail. 8 B) Describe the operation of op-amp astable multivibrator. 6 6. A) Design a comparator circuit using IC 741 which compares the input signal at two different values +5V and -5V. 8 B) Explain TTL to CMOS interface. 6 7. A) Design a square wave generator using IC 741 for the given specifications $f_0 = 5.5 \text{ KHz}$, Duty cycle = 50%. 8 B) Explain monostable multivibrator using gate. 6

Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 ELECTRONICS (New – CGPA) Paper – IX: Digital Signal Processing

Day and Date: Wednesday, 15-4-2015 Total Marks: 70

Time: 3.00 p.m. to 6.00 p.m.

Instructions: 1) Attempt five questions.

- 2) Q. No. 1 and Q. No. 2 are compulsory.
- 3) Attempt any three from Q. No. 3 to Q. No. 7.
- 4) Figures to the **right** indicate **full** marks.
- 1. A) Choose the correct answer.

1) The ROC statement for anticausal sequence

- a) Entire z-plane except $|z| = \infty$
 - b) Entire z-plane except |z| = 0
- c) Entire z-plane except |z| = 0 and $|z| = \infty$
- d) None of these

2) If a signal is shifted in time domain by k samples then the magnitude spectrum is unchanged but the phase spectrum is changed by amount

a)
$$\omega k$$

b)
$$-\omega k$$

c)
$$e^{j\omega}$$

d)
$$e^{-j\omega}$$

3) Auto-correlation is denoted by

a)
$$\gamma_{xx}(l)$$

b)
$$\gamma_{xy}(l)$$

c)
$$\gamma_{vx}(l)$$

d)
$$\gamma_x(l)$$

4) Fourier transform of a function $e^{-at}u(t)$ is

a)
$$\frac{1}{a - j\omega}$$

b)
$$\frac{1}{a+i\omega}$$

c)
$$\frac{1}{a^2 + \omega^2}$$

d)
$$\frac{1}{a^2 - \omega^2}$$



		5)	In time scaling property $x(at)$ is compressed version of the signal $x(t)$ by a factor a , when		
			a) a > 1	b) a < 1	
			c) a = 1	d) a ≠ 1	
		6)	The ROC of right hand exponential having radius $\boldsymbol{\alpha}$.	sequence is part of circle	
			a) Interior	b) Exterior	
			c) Both a) and b)	d) None	
		7)	Shifting the sequence in time dor multiplying the sequence in frequence	main by I samples is equivalent to cy domain by	
			a) $e^{-j2\pi kl/N}$	b) $e^{j2\pi kl/N}$	
			c) $e^{-j2\pi kl}$	d) $e^{j2\pi kl}$	
		8)	If sampling frequency f _s is	_ then aliasing error is observed.	
			a) $f_s \ge \omega$	b) $f_s \le 2\omega$	
			c) $f_s > 2_{\omega}$	d) $f_s \leq \omega$	
	B)	St	ate true or false .		6
		1)	Poles are roots of the denominate becomes finite.	or, or the values of z for which $x(z)$	
		2)	Direct form-II realization is also called	ed as canonic form.	
		3)	Ideal filters are practically not realize	able.	
		4)	An initially relaxed system is BIBO input produce unbounded output.	stable if and only if every bounded	
		5)	Fourier transform provides a valua analysis and design continuous time	ble technique for frequency domain signal.	
		6)	In circular advance shift sequence x(n) in clockwise direction by k samples.	
2.	A)	At	tempt any two :		10
	,		Explain FIR system. Compare FIR v	vith an IIR filter.	
		2)	Draw the spectrum of a sampled sig	nal and explain aliasing.	
		•	Explain development of Fourier trans		
	B)	•	x plain the properties of ROC of $x(z)$.		4
0					
3.	A)		ate different properties of z-transform tail.	and explain initial value theorem in	8
	B)		ate and prove time differentiation pro	perly of Fourier transform.	6
	-,		[2.0.10 mm. 0 mm.	, 	•

6

6

6

8

6

4. A) Find the linear convolution of $x_1(n)$ and $x_2(n)$ using z-transform.

$$x_1(n) = \begin{cases} 1, 2, 3, 4 \\ \uparrow \end{cases}$$
 and $x_2(n) = \begin{cases} 1, 2, 0, 2, 1 \\ \uparrow \end{cases}$.

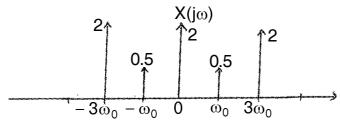
B) Determine the IZT of the following

 $x(z) = \frac{3}{z - \frac{1}{4} - \frac{1}{8}z^{-1}}$, x(n) is causal.

5. A) Obtain direct form I and II cascade form realization of a system described by

$$y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n) + \frac{1}{2}x(n-1)$$
.

- B) Explain direct Form realization of FIR system.
- 6. A) Determine the 8-point DFT of the sequence $x(n) = \{1, 2, 1, 2\}$.
 - B) Determine the inverse Fourier transform of the spectrum.



- 7. A) Why the problem of aliasing occurs during sampling process? What is the use of anti-aliasing filter?
 - B) Determine the sequence.

$$y(n) = x(n) (N) h(n)$$

where $x(n) = \begin{cases} 1, 2, 3, 1 \\ \uparrow \end{cases}$ and $h(n) = \{4, 3, 2, 2\}$.



Seat	
No.	

M.Sc. II (Semester – III) Examination, 2015 (New) (CGPA) ELECTRONICS

Paper - X: Advanced Digital Systems Design with VHDL

		te : Friday, 17-4-2 p.m. to 6.00 p.m.	2015		Max. Marks : 70
		ctions : 1) Q. No 2) Attem	. 1 and 2 are comp o pt any three questo es to the right indic	ion from Q. No. 3	to 7 .
I. A)	CI	noose the correct	alternative :		8
	1)	-	antiation statements b) Sequential		tatement. d) Both (a) and (b)
	2)		ent in VHDL is carrie b) assert		
	3)		plemented for b) analog		d) none of these
	4)	a) one-dimensi	the '&' operator is onal array sional array		b)
	5)		esign include b) technology		
	6)		type of de		
	7)	The most comm	only used logic bloo b) FPGA	•	le present in d) all of these
	8)	Every entity has a) different	its archi	tecture. c) mixed	d) entity P.T.O.

SLR-SP - 245



	B)	State true or false.	6
		1) A configuration is used to bind an architecture body to its entity declaration.	
		2) IN:=X "01_11_00" statement assigns binary value.	
		3) The expression with syntax of NOR operator is legal.	
		4) The anti-fuse programming technique is a reprogramming technique.	
		5) FPGA architecture is more granular as compared to CPLD.	
		6) In back-end design the physical source is created from logic source.	
2.	A)	Attempt any two.	10
		1) Explain the concept of HDL.	
		2) Discuss component declaration using half-adder.	
		3) Explain the concept of macro cell	
	B)	Draw the structure of CPLD.	4
3.	A)	Explain in detail basic language elements in VHDL.	10
	B)	Write a VHDL Code for Full-adder.	4
4.	A)	Clarify the PLD in detail. Explain FPGA.	9
	B)	Write a VHDL Code for 4 to 1 multiplexer.	5
5.	A)	State the various architecture bodies and explain in detail mixed style of body with suitable example.	9
	B)	Write a VHDL Code for shift register.	5
6.	A)	Explain in detail EDA tools.	9
	B)	Write VHDL Code for ALU.	5
7.	A)	Discuss in detail packages and libraries.	9
	B)	Explain resolution function.	5

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Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 ELECTRONICS (New) (CGPA)

Elect	tive – I, Paper – X	XI : ARM Micro	ocontroller and s	Sys	tem Design
Day and D	Date : Monday, 20-4-	2015			Max. Marks : 70
Time: 3.0	0 p.m. to 6.00 p.m.				
Ins	3) Atter	stion 1 and 2 com mpt any three fro	npulsory.		
1. A) Ch	noose the correct an	swer:			8
1)	is high	nest priority excep	otion.		
	a) FIQ	b) IRQ	c) Reset	d)	Abort
2)	To improve the cod	le density ARM u	ses		
	a) Thumb 16 bit ins	struction set			
	b) Jazzale 32 bit ir	struction set			
	c) 64 bit instruction	n set			
	d) None of these				
3)	In LPC 2148, when in	nternal reset is rem	noved the processor b	oegii	ns executing at
	a) address 0	b) address 1	c) address 5	d)	address 7
4)	mode is non-	-privilaged mode.			
	a) user	b) abort	c) supervisor	d)	undefined
5)	In LPC 2148, the I ²	C bus supports b	it rates upto		
	a) 100 Kbits/s	b) 200 Kbits/s	c) 300 Kbits/s	d)	400 Kbits/s
6)	Thumb instruction s	set executes	bit instructions	S .	
	a) 8	b) 4	c) 16	d)	none of these

		7) are banked re	egisters.			
		a) r ₁₄ – r ₁₇	b) $r_7 - r_{13}$	c) $r_0 - r_7$	d) $r_8 - r_{14}$	
		8) In RAM processor,	register file conta	ains total	_ registers.	
		a) 20	b) 27	c) 37	d) 40	
	B)	State True or False :				6
		1) All instructions in A	.RM are condition	ally executed.		
		2) The ARM processo	ors doesn't suppo	rt byte addressibilit	ïy.	
		3) In LPC 2148, I ² C b	us is unidirection	al.		
		4) The LPC 2148 cont	tain 3 UART's.			
		5) ARM core is 64 bit	processor.			
		6) r ₁₃ register is the s	tack pointer.			
2.	A)	Attempt any two:				10
		1) Describe the pipelin	ning of ARM micr	ocontroller.		
		2) Write a note on SP	SR.			
		3) Explain modes of A	RM microcontrol	ler.		
	B)	Mention the salient fea	atures of LPC 214	·8.		4
3.	A)	Describe the ARM cor	e philosophy in d	etail.		8
	B)	Write a note on AMBA	bus architecture	of ARM microconti	roller.	6
4.	A)	Explain with suitable b	lock diagram the	architecture of LPC	2148.	8
	B)	Describe memory orga	anisation of LPC 2	2148.		6
5.	A)	Describe in detail inter	rupts and except	ion of ARM microco	ontroller.	8
	B)	State and explain the r	nomenclature use	ed for ARM microco	entroller with	_
		example.				6
6.	A)	Explain ARM and Thui	mb ISA in detail.			8
	B)	Write a note on differe	nt operating mod	es in ARM.		6
7.	A)	Describe the designing to measure temperature	-	ontroller based an e	mbedded system	8
	B)	Explain barrel shifter in	n detail.			6



Seat	
No.	

M.Sc. – II (Semester – III) Examination, 2015 ELECTRONICS (New) (CGPA)

ELECTRONICS Elective – I : Paper – XI : 0	S (New) (CGPA) CMOS Design Technolo	gies
Day and Date : Monday, 20-4-2015 Time : 3.00 p.m. to 6.00 p.m.		Total Marks: 70
Instructions: 1) Q. 1 and Q. 2 are 2) Solve any three to 3) Figure to the right 4) Draw necessary of allowed.	rom Q. 3 to Q. 7 .	lator is
1. A) Choose correct alternative :		8
 The voltage at which MOS device voltage. a) Threshold c) Ground ln D-region P-device is in a) Saturation c) Both a) and b) 	b) Supply d) None of these	
3) When channel length (L) of n-c change.	- -	is
a) β_n c) $\beta_n \beta_p$	b) β_pd) both a) and c)	
4) In saturated load inverter gate of	the p-device connected to _	
a) V _{dd}	b) V _{ss}	
c) Ground	d) Output	



Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 ELECTRONICS (New) (CGPA)

Pape		ONICS (New) (CGPA) al Instrumentation (Elective	e – II)
Day and Date: Wee Time: 3.00 p.m. to	-	15	Total Marks : 70
Instruction	3) Attempt any	equestions. and 2 are compulsory . y three from Q. 3 to Q. 7 he right indicates full marks.	
1. A) Choose cor	rect answer:		8
1) The	type of	electrode is used for EMG meas	urement.
a) Limb	b) Needle	
c) Surfa	ce d)) Floating	
2) The cell	membrane in exci	ted state impedes the entry of $_$	lons.
a) Na+	b)) CI ⁺	
c) K ⁺	d) P ⁺	
3) The	is th	ne record of potential generated I	by brain.
a) ECG	b) EEG	
c) EMG	d) PCG	
4) The	mV is the	e resting potential of the cell.	
a) + 20	b)) +90	
c) -90	d)) -20	
5) The ultra	asonic frequencies Hz.	utilized for medical instrumentati	on ranges from
a) 1 to 1	5 K b)) 1 to 15 M	
c) 1 to 1	5 G d)) 1 to 20 G	

LR-	SP-	248	-2-		
	6)	The pH electrode emf ch	nanges by	Volt per 1°C.	
		a) 0.02 micro	b) 0.02 m		
		c) 0.2 m	d) 0.2 micro		
	7)	The heart rate is controlle activity.	ed by	_ system and partially by	
		a) Automatic nervous, h	armonic		
		b) Harmonic, automatic	nervous		
		c) Controlled nervous, h	armonic		
		d) Harmonic, controlled	nervous		
	8)	The contact impedance the body tissue measure		than the electrical impedance of kin.	
		a) Less	b) Greater		
		c) Equal	d) None of thes	se	
В) St	ate true or false :			6
	1)	Pre-gelled disposable e	lectrodes genera	ally suffers from motion artefacts.	
	2)	X-ray picture is called ra	diography.		
	3)	The differential amplifie currents.	r always provide	es the protection against leakage	
	4)	The body fluid is ionic.			
	5)	The positive potential of potential.	of the cell memb	orane during excitation is action	
	6)	The body fluid is slightly	alkaline.		
2. A) At	tempt two :			10
	1)	Explain skin contact imp	edance.		
	2)	Draw neat labeled engir	neering diagram	of cardiovascular system.	
	3)	Write the basics of diag	nostic radiology.		
В) Ex	plain contact impedance			4

	-3-	SLR-SP - 248
3.	A) Classify the electrode. Explain the surface electrodes in detail.	9
	B) Write a note on blood pressure measurement.	5
4.	A) Explain the origin of bio-potential in detail.	9
	B) Write a note on chemical biosensors.	5
5.	A) Explain in detail microcontroller based ECG recording system.	9
	B) Explain the source of noise.	5
6.	A) Explain the SA and AV node in detail.	9
	B) Explain the architecture of X-ray machine.	5
7.	A) Explain in detail basic recording system.	9
	B) Write a note on pO ₂ electrode.	5



Seat	
No.	

ELECTRONICS Paper – XII : Digital Comm	(New-CGPA)
Day and Date : Wednesday, 22-4-2015	Max. Marks : 70
Time: 3.00 p.m. to 6.00 p.m.	
Instructions: 1) Q. 1 and Q. 2 are con 2) Solve any three from 3) Figures to the right in 4) Draw necessary diag 5) Use of scientific calc	n Q. 3 ro Q. 7 . ndicate marks. gram wherever necessary.
1. A) Choose the correct alternate of the following	owing:
 In Shannon's channel capacity the than channel capacity. 	eorem rate of information is
a) greater	b) less
c) both a) and b)	d) none of these
2) Source coding redundancy	<i>1</i> .
a) decreases	b) increases
c) unaffected	d) none of these
3) The amplitude level is constant in _	quantization.
a) Uniform	b) Non-uniform
c) Robert	d) None of these
4) The important element of digital cor	nmunication is
a) Signal	b) Sampling
c) Encoder	d) All of these



		5)	PCM modulation is type of	modulation.	
			a) analog	b) digital	
			c) phase	d) none of these	
		6)	Quantization is process of		
			a) Rounding off	b) Approximation	
			c) Both a) and b)	d) None of these	
		7)	Granular noise present in	modulation.	
			a) Adaptive delta	b) Delta	
			c) ASK	d) FSK	
		8)	In PSK modulation	detection method is used.	
			a) coherent	b) synchronous	
			c) non-coherent	d) none of these	
	B)	Sta	ate true or false :		6
		1)	Block parity check is error detec	tion technique.	
		2)	The hamming code is error conn	ection method.	
		3)	In discrete channel both input an	d output are digital.	
		4)	Quantization is nothing but conv	ersion of analog signal into digital signal.	
		5)	DTMF stand for Digital Tone Mul	ti Frequency.	
		6)	The combined effect of sampling output.	and quantization produces the quantized	
2.	A)	Ar	swer any two of the following:		10
		1)	Write a note on DTMF.		
		2)	Explain parity check error detect	ion technique.	
		3)	Explain power and energy of san	npling signals.	
	B)	W	rite a note on quantization.		4

SLR-SP - 250

Seat	
No.	

M.Sc. (Part - II) (Semester - III) Examination, 2015 **ELECTRONICS (New) (CGPA)**

Elective – I	I:Paper – XII:0	CMOS Analog	Ćircuit Design	
Day and Date: Wedneso Time: 3.00 p.m. to 6.00	-		Total Marks :	: 70
Instructions:	 Attempt five qu Question 1 and Attempt any the Figures to the r 	2 are compulso ree from Q. 3 to Q	0.7.	
1. A) Choose correct a	alternative.			8
 In MOS trans Strongly Moderate 	sistor, the substrate	should b) Weak d) None of the	-	
In case of claa) Passive			d as Load. d) None of these	
used a) Source fo	·	b) Class-A	CMOS Amplifier can be	
4) The gain of s a) Ci∗CF	witched capacitor i	nverting amplifier		
5) The SiO ₂ lay a) Depletior c) Barrier po	n layer	Gate of MOS tranb) Conductive d) None of the	•	
	d the bulk both are ance is given by	connected to gro	ound, then small signal	
a) $R = \frac{\lambda}{1D}$	b) $R = \lambda \cdot ID$	c) $R = \frac{1}{\lambda \cdot ID}$	d) $\frac{\text{ID}}{\lambda}$	

2.

3.

4.

5.

6.

7.



	nected to one drain irce	ed with same supply and gates of both , then the circuit will be b) Current sink d) None of these	
8) When the gate neath of the gat	voltage reaches to t	threshold voltage, then substrate under	
a) Potential hilc) Inverted	.l	b) Potential welld) Saturated	
2) For switched ca3) The parasitic re4) For NMOS tran5) Output CMOS capacitive load	nsistors acts as currepacitor circuit the consistor exhibit fringinsistor of CMOS and amplifiers are typical.	rent sink, when gate potential is $V_{DD}/2$. locks ϕ_1 and ϕ_2 should be out of phase. ng effect. nplifier acts as active load. cally designed for resistive as well as ow frequency applications.	6
2) Write a note on	f the following. ned capacitor sumr class-A CMOS An ean by CMOS capa	nplifier.	10
B) Write a note on NM	10S transistor as a	switch.	4
A) Describe single staB) Write a note on bar		r and explain large signal model. e source.	8 6
A) Describe basic prin switched capacitorB) Write a note on MC	integrator circuit.	apacitor. With suitable diagram explain	8
A) With suitable block ofB) Write a note on cur	_	ngle stage CMOS operational amplifier.	8 6
A) Describe indetail CB) Write a note on BiC		mplifier.	8 6
A) Describe the effect capacitor circuit.	of phase and frequ	iency on performance of switched	8
B) Describe the current	nt mechanism in NI	MOS transistor.	6

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Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 ELECTRONICS (Old) Paper – IX: Digital Signal Processing

	Paper	– IX:Digita	I Signal Proce	essing
Day and Date : V	Vednesday,	15-4-2015		Max. Marks: 100
Time: 3.00 p.m.	to 6.00 p.m	1.		
Instructions :	2) Question3) Attemp	r five questions. on 1 and 2 comp t any three from s to right indicat	oulsory . m Q. 3 to Q. 7 .	
1. a) Choose	the correct a	answer.		8
a) Er b) Er c) Er	ntire z-plane ntire z-plane	ent for causal see except $ z = \infty$ except $ z = 0$ except $ z = 0$ a	·	
2) Enerç a) Fii	gy of power a	signal is b) Infinite	c) Zero	d) 1
•	nsform of de	elayed unit impu b) z ^k	•	d) n-δ(n)
a) Re	nd the invers esidue metho indowing me	od	b) Convoluti d) Impulse ii	
a) Co	t of imagina omplex z-pla onvolution	-	real part is called b) Real z-pla d) None	
and ir a) Qı	nput is called uantization e	d error	b) Quantiza	
c) Bo	oth a) and b)		d) None of tl	nese



- 7) The signal x(t) is said to be an odd signal if it statisfies the condition
 - a) x(-t) = -x(t)

b) x(-t) = x(t)

c) x(t) = -x(t)

- d) n = 0
- 8) The amplitude of unit impulse function is 1 at
 - a) n = 0
- b) n = 1
- c) n < 0
- d) n > 0

- b) Fill in the blank.
 - 1) Recovery of CT signal is possible from the sampled data by the process of [modulation, interpolation]
 - 2) The z-transform for the DT sequence x(n) = u(n) is

$$\left[\frac{1}{z-1}, \frac{z}{z-1}\right]$$

- 3) The ROC of right hand exponential sequence is _____ part of circle having radius α . [exterior, interior]
- 4) Dynamic system are with [memory, memory less]
- 5) A signal which cannot be described by any mathematical expression is called as _____ signal. [random, detministic]
- 6) $T[x(n)] = e^{x(n)}$ is _____ system. [linear, non linear]
- c) State true or false.

6

- 1) A system is time invariant if its input-output characteristics do not change with time.
- 2) Causal FIR system is recursive system.
- 3) An initialy relaxed system is BIBO stable if and only if every bounded input produces unbounded output.
- 4) If sampling frequency fs is less than w then an error called aliasing error.
- 5) In bilateral z-transform the summation is carried out from $-\infty$ to ∞ .
- 6) A fourier transform is calculated only discrete points then it is called as DFT.

2. Attempt any four.

20

- 1) Explain 2-transformer and ROC.
- 2) What is an FIR filter? Compare an FIR filter with an IIR filter.
- 3) Write a note on standard test signal.
- 4) Write a note on sampling.
- 5) Obtain z-transform of $x(n) = a^n u(n)$ using scaling property.
- 3. a) What is relation between DFT and z-transform? Explain what is convolution? 10
 - b) Obtain the linear convolution of two sequences defined as 10

$$x(n) = u(n) - u(n-3)$$

$$h(n) = u(n-1) + u(n-2) - u(n-4) - u(n-5)$$

using circular convolution.

4. a) Develop parallel form realization for the digital filter with transfer function **10**

$$H(z) = \frac{1 + 2z^{-1} + z^{-2}}{1 - 0.75z^{-1} + 0.125z^{-2}}$$

b) Determine IZT of the following:

$$X(z) = \frac{1 - \frac{1}{2}z^{-1}}{1 + \frac{3}{4}z^{-1} + \frac{1}{8}z^{-2}}, |z| > \frac{1}{2}.$$

- 5. a) State different properties of z-transform and explain any two in detail.
 - b) Obtain linear convolution of following sequence using z-transform.

$$x_1(n) = \{1, 2, 3, 4\} \text{ and } x_2(n) = \{1, 2, 0, 2, 1\}$$



- 6. a) Explain how to represent discrete time system via difference equation. Also explain properties of discrete time system.
 - b) What is overlap save method of fast convolution?
- 7. a) Determine the z-transform of following equation:
 - i) $x_1(n) = \{2, 1, 3, 4, 0\}$
 - ii) $x_2(n) = \{2, 1, 2, 1, 0, 1\}$
 - b) Determine whether the following systems are linear or not:
 - i) y(n) = nx(n)
 - ii) y(n) = cosx(n).

SLR-SP - 252



Seat	
No.	

M.Sc. – II (Semester – III) Examination, 2015 ELECTRONICS (Old)

Paper - X: Advanced Digital Systems Design with VHDL

•	аро. ж. жата	inoda Digital	0,0	ioinio Boolgi			
•	Date : Friday, 17-4-2 0 p.m. to 6.00 p.m.	015				Total Marks: 10)0
Ins	3) Atte	mpt any five questions 1 and 2 ampt any three the state of the right	are co from d	mpulsory . questions 3 to			
1. A) Se	elect correct answer	:					8
1)	The	are the EOA too	ols for	back-end des	sign pı	rocess.	
	a) Programming to	ools	b)	Implementation	on tool	ls	
	c) Physical verifica	ation	d)	All of these			
2)	Error management	in VHDL is carr	ried o	ut by	s	tatement.	
	a) Generate		b)	Assert			
	c) Assignment		d)	All of these			
3)	The '&' operator is	called		_operator.			
	a) addition		b)	multiplication			
	c) concatenation		d)	both a) and b))		
4)	Every entity has its		_arch	itecture.			
	a) mixed	b) own	c)	different	d) no	one of these	
5)	The test bench is u	sed for		of design			
	a) net-list		b)	verification			
	c) programming		d)	none of above)		
6)	The	_ statement is u	used to	o iterate throug	gh a s	et of	
	sequential stateme	nts.					
	a) wait	b) null	c)	loop	d) if-	then	



	7)	Thea constant.	assignment	operator is used t	to assign a value to	
		a) <=	b) :=	c) =>	d) all of these	
	8)	Component instanti	ation statements	are	_statements.	
		a) assertion	b) sequential	c) concurrent	d) none of above	
B)	Fill	l in the blanks :				6
	1)	Simulation is a	way	of emulating the b	oehaviour of a circuit.	
		(logical/mathematic	cal)			
	2)	The statement 'wai	t for O ns;' mean	s to wait for	delta cycle.	
		(one / zero)				
	3)	The 16 # A # <u>F</u> 5 rep	oresents			
		(10 * 16 ⁵ / 10 * 16 ·	* 5)			
	4)	The Exit and next s	tatement are use	ed only	a loop.	
		(outside / inside)				
	5)	The content of pack	=	iIC _ 1164 are acc	cessed by using	
		(library / type)				
	6)	The generate stater	ment is	statement		
		(sequential/concu	rrent)			
C)	Sta	ate true or false :				6
	1)	The character litera	ıls are always wr	itten between sing	gle quotes.	
	2)	The operators NAN	ID and NOR are	associative.		
	3)	The process staten	nent is itself a se	quential statemer	nt.	
	4)	The wait statement a process.	provides an alte	rnate way to susp	end the execution of	
	5)	The statement IN:	= B "01 – BO" a	ssigns binary valu	ıe.	
	6)	Items declared in a units by using the u	. •		d by other design	



2.	Solve any four:	20
	1) State the advantages of VHDL.	
	2) Explain syntax of process statement.	
	3) Explain logical operators is in VHDL.	
	4) Explain component declaration with OR gate.	
	5) Write the VHDL code for Half Adder.	
3.	A) Explain in detail basic language element of VHDL.	12
	B) Write the VHDL code for 8 to 1 mux.	8
4.	A) Discuss in detail packages and literaries.	12
	B) Write the VHDL code for 4-bit shift register.	8
5.	A) Discuss the various types of architecture bodies and explain 4 to 2 encod for structural style of modeling.	er 12
	B) Write the VHDL code for ALU.	8
6.	A) Write a note on: 1) Entity 2) Architecture.	12
	B) Write the VHDL code for 7-seg display.	8
7.	A) Explain in detail structural layout and generies.	12
	B) Write the VHDL code for 4-bit counter.	8



Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 (Elective – I) ELECTRONICS (Paper – XI) (Old) Advanced Microcontroller Based System Design

	Advanced	Microcontroll	er Based Syste	em Design	
•	Date: Monday, 20- 0 p.m. to 6.00 p.m			Total. Marl	ks: 100
In	3) A 4) F	Question 1 and 2 ttempt any thre	are compulsory . e questions from (h t indicate full ma		
1. A) C	hoose correct alte	rnative.			8
1)	PIE1 Resistor us	ed to Enable			
	a) Interrupt	b) WDT	c) USART	d) ADC	
2)	To shield cable to on cable.	prevent Electror	nagnetic effect we	usecoati	ng
	a) soft iron		b) ferromagne	etic material	
	c) plastic		d) both a and	b	
3)	gives	frequency as ou	tput signal.		
	a) Optocoupler		b) Tachomete	er	
	c) Thermocouple	е	d) RTD		
4)	Reset circuit of F	PIC consist of			
•	a) Diode, Resist	tor, Capacitor	b) Switch, Ca	pacitor	
	c) Switch, Diode)	d) Switch, Did	ode, Capacitor, Resi	stor
5)	In current to vol	tage conversior	ı input voltage (V _i	_n) and R _i replaced	by
	a) current	b) voltage	c) V _{in}	d) V _{out}	



	6)	Sleep and powerdo	own mode use to _			
		a) reset μc	b) turn of μc	c) save power	d) none of these	
	7)	PIC has program n	nemory 8 kbyte w	rith bi	t wide.	
		a) 10	b) 16	c) 14	d) 12	
	8)	Postscaler is used	to scale the			
		a) output	b) clock source	c) both a and b	d) input	
B)	Fill	l in the blanks.				6
	1)	ADC of AVR have	inpu	it channels (8/10)		
	2)	To send data on s En pin of LCD mad			nicro-controller, the igh)	
	3)	Coupler are use to	two	devices. (connect	/isolate)	
	4)	Ro from AVR resis load data)	tor file used for _	mem	ory. (load program/	
	5)	Power on reset of A	AVR is	_(Active high/Act	ive low)	
	6)	Port E is	(3 bit/4 bit)			
C)	Sa	y true or false .				6
	1)	Read relay is filled	with nitrogen gas	S.		
	2)	Optocoupler is use	ed for isolation hig	gh voltage and low	voltage devices.	
	3)	Timer 0 of AVR is	16 bit.			
	4)	Timer 1 of PIC is 1	6 bit.			
	5)	PCON Resistor us	ed to save power	·.		
	6)	Global Interrupt Er Resistor.	nable (GIE) bit of	PIC micro-control	ler consist in status	



2.	At	tempt any four .	20
	1)	Explain Internal ADC of AVR.	
	2)	Explain need of isolation.	
	3)	Write note on timer 0 of PIC 16F877.	
	4)	Convert voltage into current.	
	5)	Explain the internal WDT of AVR.	
3.	A)	Write note on 4 to 20 mA current loop and I to V conversion.	12
	B)	Write a program to on-off LED's which are connected to port E, draw circuit diagram for PIC 16F877.	8
4.	a)	Draw minimum hardware module for AVR and explain block diagram of micro-controller based system.	10
	b)	Explain timer 2, also explain PWM technique using timer 2.	10
5.	a)	Draw neat labeled diagram of clock and reset circuit. Explain it in detail of AVR.	10
	b)	Write note on timer 1 of pic 16F877.	10
6.	a)	Write note on types of optocoupler, explain in brief.	10
	b)	Draw and explain architecture of PIC 16F877.	10
7.	a)	Write note on V to F convertion.	10
	b)	Explain in brief electromagnetic shielding and grounding	10



Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 (Elective – I) ELECTRONICS (Paper – XI) (Old) Advanced Microcontroller Based System Design

	Advanced	Microcontroll	er Based Syste	em Design	
•	Date: Monday, 20- 0 p.m. to 6.00 p.m			Total. Marl	ks: 100
In	3) A 4) F	Question 1 and 2 ttempt any thre	are compulsory . e questions from (h t indicate full ma		
1. A) C	hoose correct alte	rnative.			8
1)	PIE1 Resistor us	ed to Enable			
	a) Interrupt	b) WDT	c) USART	d) ADC	
2)	To shield cable to on cable.	prevent Electror	nagnetic effect we	usecoati	ng
	a) soft iron		b) ferromagne	etic material	
	c) plastic		d) both a and	b	
3)	gives	frequency as ou	tput signal.		
	a) Optocoupler		b) Tachomete	er	
	c) Thermocouple	е	d) RTD		
4)	Reset circuit of F	PIC consist of			
•	a) Diode, Resist	tor, Capacitor	b) Switch, Ca	pacitor	
	c) Switch, Diode)	d) Switch, Did	ode, Capacitor, Resi	stor
5)	In current to vol	tage conversior	ı input voltage (V _i	_n) and R _i replaced	by
	a) current	b) voltage	c) V _{in}	d) V _{out}	



	6)	6) Sleep and powerdown mode use to						
		a) reset μc	b) turn of μc	c) save power	d) none of these			
7) PIC has program memory 8 kbyte with bit wide.								
		a) 10	b) 16	c) 14	d) 12			
	8) Postscaler is used to scale the							
		a) output	b) clock source	c) both a and b	d) input			
B)	Fill	l in the blanks.				6		
	1)	ADC of AVR have	inpu	it channels (8/10)				
 To send data on smart LCD, which is connected to micro-controller, the En pin of LCD made (high to low/low to high) 								
	3)	Coupler are use to	two	devices. (connect	/isolate)			
	4)	Ro from AVR resis load data)	tor file used for _	mem	ory. (load program/			
	5) Power on reset of AVR is (Active high/Active low)							
	6)	Port E is	(3 bit/4 bit)					
C)	Sa	y true or false .				6		
	1)	Read relay is filled						
	Optocoupler is used for isolation high voltage and low voltage devices.							
3) Timer 0 of AVR is 16 bit.								
	4)							
	5)							
	6)	Global Interrupt Enable (GIE) bit of PIC micro-controller consist in status Resistor.						



2.	At	tempt any four .	20
	1)	Explain Internal ADC of AVR.	
	2)	Explain need of isolation.	
	3)	Write note on timer 0 of PIC 16F877.	
	4)	Convert voltage into current.	
	5)	Explain the internal WDT of AVR.	
3.	A)	Write note on 4 to 20 mA current loop and I to V conversion.	12
	B)	Write a program to on-off LED's which are connected to port E, draw circuit diagram for PIC 16F877.	8
4.	a)	Draw minimum hardware module for AVR and explain block diagram of micro-controller based system.	10
	b)	Explain timer 2, also explain PWM technique using timer 2.	10
5.	a)	Draw neat labeled diagram of clock and reset circuit. Explain it in detail of AVR.	10
	b)	Write note on timer 1 of pic 16F877.	10
6.	a)	Write note on types of optocoupler, explain in brief.	10
	b)	Draw and explain architecture of PIC 16F877.	10
7.	a)	Write note on V to F convertion.	10
	b)	Explain in brief electromagnetic shielding and grounding	10



Seat	
No.	

M.Sc. – II (Semester – III) Examination, 2015 ELECTRONICS (Old)

	Paper – XI		ONICS (OId) I : Digital Co	ommunication	
•	Date : Monday, 20 0 p.m. to 6.00 p.r			Max. Marks	s : 100
Ins	3) Fi	olve any three igures to the ri g	from Q. 3 to Q ght indicate ma). 7 .	d.
1. A) Ch	noose correct alte	ernative :			8
1)	In communicatio	n the sampling	technique impr	over the	
	a) high efficiency	y	b) cheaper eq	uipments	
	c) high speed co	mmunication	d) all of these		
2)	The earth station	n receivers com	mon up-down	converter hasI	F.
	a) 50 MHz		b) 100 MHz		
	c) 70 MHz		d) 120 MHz		
3)	accomplished w	-		then transmission may b e.	е
	a) C > R ²		b) R << C		
	c) C < R		d) C < R ²		
4)	The	$_{ m l}$ is the analog r	nodulation tech	nique.	
	a) PWM	b) PCM	c) ADM	d) DM	
5)	In line coding AM	/II is subcoding	of	method.	
	a) bipolar	b) unipolar	c) polar	d) biphase	
6)	The quantization	n error is functio	n of	<u> </u>	
	a) signal amplitu	de	b) intervals be	etween levels	
	c) signal phase		d) signal frequ	iency	



	7)	ISDN user which of cable		
		a) Coaxial	b) Fiber optic	
		c) Twisted pair	d) Speaker	
	8)	Which of the following type of HPA	A is not used in earth station	
		a) TWT	b) Magnetron	
		c) Klystron	d) Transistor	
B)	Fil	ll in the blanks :		6
	1)	The form of modulation used in A	DSL is	
		(QAM/PSK)		
	2)	Bandwidth of ASK is	than FSK.	
		(less/higher)		
	3)	The is the one way	communication system.	
		(simplex/duplex)		
	4)	The ADSL usertype	e of multiplexing.	
		(FDM/TDM)		
	5)	In modem the space signal is rep	resented by frequency.	
		(1070 Hz/1225 Hz)		
	6)	The centre of gravity of earth is c	alled	
		(geocentre/geostation)		
C)	Sta	ate true or false :		6
	1)	The highest distance point from t	the earth is called apogee.	
	2)	Digitization is process of roundin level.	g of signal to particular desired standard	
	3)	Asynchronous transmission is fa	rter than synchronous transmission.	
	4)	The modulation technique is used	as encoding data only when analog signal.	
	5)	With QAM a 56 kbps signal can b	oe transmitted within a 3kHz bandwidth.	
	6)	The hamming code is error detec	ction method.	



2.	Answer any four:	20
	1) Describe block diagram of modem.	
	2) Explain digital reception in ADM.	
	3) Explain sampling theorem.	
	4) Explain any two line coding technique.	
	5) Explain the structure of DTMF.	
3.	A) Explain block diagram of digital communication.	10
	B) What is hamming code? Explain its structure and correct the error for 10110010 code.	10
4.	A) Explain in detail satellite station.	10
	B) Explain in detail ADM transmission system and how it is differs from DM.	10
5.	A) What is analog and digital base band transmission? Explain PWM and PSK.	12
	B) Explain error correction method.	8
6.	A) Explain in detail ISDN.	12
	B) What is digital communication technique and explain FSK technique.	8
7.	A) What is quantization? Explain uniform quantization.	10
	B) Explain in detail signals in digital communication.	10

SLR-SP - 256



Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 ELECTRONICS (Old)

(Elective – II) Paper – XII : Medical Instrumentation

Day and Date: Wednesday, 22-4-2015 Total Marks: 100

Time: 3.00 p.m. to 6.00 p.m.

Instructions: 1) Solve five questions.

- 2) Question 1 and 2 are compulsory.
- 3) Attempt any three from Q. No. 3 to Q. No. 7.
- 4) Figures to the **right** indicate **full** marks.

8

- The recording of electrical activity associated with the functioning of heart is known as
 - a) ECG

b) EMG

c) EEG

- d) EOG
- 2) Typical EMG signal ranges from
 - a) .01-0.5 mV

b) 0.1-0.5 mV

c) 0.1-0.5 V

- d) None
- 3) The most commonly used electrodes in patient monitoring are
 - a) SCALP electrode
 - b) Needle electrode
 - c) Skin Electrode
 - d) Contact Electrode
- 4) Typical thermodynamic pressure for arterials system is
 - a) 30-300 mmHg

b) 5-15 mmHg

c) 6-25 mmHg

- d) None of the above
- 5) The isolation amplifiers are optimized for signal frequencies in range of
 - a) 0.05-100 Hz
- b) DC-1 KHz
- c) 1 KHz-10 KHz d) None



- -2-6) T wave represents a) Repolarization of both ventricular b) Time which an impulse leaving the SA node c) Time taken by heart impulse to travel through inter ventricular system d) None of the above 7) The normal rate of heart at rest b) 68 beats/min a) 72 beats/min c) 82 beats/min d) 100 beats/min 8) The X-ray picture is called a) Electroencephalogram b) Radiograph c) Electrocardiogram d) None b) Fill in the blanks: 1) The most commonly used electrodes for ECG recording are the chloride silver having approximately diameter of _____ mm. [6-8, 10-12] 2) A _____ diameter silver cathode constitutes a pO_2 measuring electrode. [14 mm, 24 mm] 3) The spectral analysis transforms the analog EEG signal recorded on _into a signal displayed on frequency axis. [Time axis, Volt axis] 4) Isolation amplifiers are commonly used for providing protection against _current. [Leakage, Excess] 5) Resistance of _____ shows a fall with increase in temperature. [Thermister, posisters]
- c) State True or False.

 $[10^{-12}, 10^{-10}]$

6

6

1) Skin electrode is of a value much greater than the electrode impedance of body tissue as measured beneath the skin.

6) The X-rays in medical diagnostic region have wavelength of the order of

2) Human cells have a typical membrane thickness of 0.02 mm.

 $_{\rm min}$ m and they propagate with a speed of 3×10^{10} cm/s.

- 3) Manganese, cobalt and nickel have a large positive temperature coefficient of resistance.
- 4) X-rays are at high wavelength end of electromagnetic spectrum.
- 5) EMG is usually recorded by using surface electrodes or needle electrodes which are directly inserted into body.
- 6) Limb electrodes are generally made of German silver.



2.	Att	empt any four:	20
	1)	Why proper grounding is required ? Explain the term ground loop with necessary diagrams.	
	2)	List electrodes for ECG, EEG and EMG. Explain any one in detail.	
	3)	Write a note on X-ray imaging.	
	4)	Explain how to measure pH of blood.	
	5)	Write a short note on measurement of bio potentials.	
3.	a)	With basic principle and block diagram explain computerized analysis of ECG.	20
	b)	Explain concept of blood pressure and technique for measurement of BP.	
4.	a)	With proper block diagram explain complete blood gas analyzer in detail.	20
	b)	Write a note on blood oxygen sensor.	
5.	a)	What is ECG? Explain with basic principle of ECG, an isolation preamplifier used in modern ECG machines.	20
	b)	Describe the architecture of MRI system.	
6.	a)	With basic principle and block diagram explain EMG in detail.	20
	b)	What is concept of electric impedance? Explain impedance bridge circuit in detail.	
7.	a)	Using Nernst equation explain how to find the potential of a cell membrane. Explain any one type of potentiometric sensors.	20

b) With neat circuit diagram explain instrumentation amplifier.



Seat	
No.	

M.Sc. (Part – II) (Semester – III) Examination, 2015 (Elective – II) ELECTRONICS (Old) Paper – XII: Computer Aids for VLSI Design

	•	•	ter Aids for V	` '	
•	Date : Wednesday 00 p.m. to 6.00 p.r			Max. Marks : 10	00
Ins	3) A	uestions 1 and ttempt any thr e	stions. 2 are compulso ee from Q. 3 to G ght indicate full	Q. 7.	
1. A) Cł	noose correct ans	swer:			8
1)	In computer aide considered.	ed VLSI design		characteristics should be	
	a) 3	b) 4	c) 2	d) 1	
2)	The cell that doe level of hierarchy			y other cell is at the top	
	a) leaf cell		b) root cell		
	c) composition	cell	d) none of thes	e	
3)		is the behaviou	ıral level design (environment.	
	a) Microwind	b) Xilinx	c) Proteuos	d) None of these	
4)	In stick diagram	, the diffusion la	yer is of	colour.	
	a) Red	b) Green	c) Yellow	d) Blue	
5)	In computer aide small units called			ing but aggregation of	
	a) Cell	b) Blocks	c) Bus	d) Switches	
6)	The FPGA consi	ist of combination	on of		
	a) IOB	b) CLB	c) Cell	d) None of these	



	7)	In temporal view	is used as input vectors.	
		a) clock pulse	b) current	
		c) raster scan	d) none of these	
	8)	Following tool is used for static	analysis	
		a) Timing diagram	b) Routing	
		c) GRC	d) None of these	
B)	Fil	l in the blanks :		6
	1)	To express the behavioural value language. (Description, Assembly)	riew, the design consist of	
	2)	The process of drawing a schell (Schematic Capture, Algorithm)	matic of the circuit is called ic Capture)	
	3)	When routing is done on four side called(Switch, Switch box)	des of a rectangular area, then the router is	
	4)	is the process of p (Placement, Routing)	ositioning the cells.	
	5)	Integrated circuits are manufact (wafer, boat)	tured on large disk of silicon, called	
	6)	Every objects in the VLSI devic (attributes, abstraction)	e are associated with	
C)	Sta	ate True or False :		6
	1)	A Group of about 40 wafers is o	called boat load.	
	2)	The FPGA based design is sem	nicustom design.	
	3)	The microwind design tool is ba	sed on component level design.	
	4)	Geometrical rule checking is ba	ased on power consumption.	
	5)	The PLA consist of CLB.		
	6)	Behavioural is the first stage of	VLSI design.	



2.	An	swer any four of the following:	20
	1)	Write a short note on structural view.	
	2)	What do you mean by programmable gate array?	
	3)	Write a note on design flow.	
	4)	Describe the term behavioural level simulation.	
	5)	Write a note on placement and routing.	
3.	a)	What do you mean by synthesis tools? Describe cell contents generation and manipulation.	12
	b)	With labelled diagram describe the architecture of the FPGA.	8
4.	a)	What do you mean by dynamic analysis? Explain logic level analysis in detail.	12
	b)	Write a note on temporal views.	8
5.	a)	What do you mean by representation? Describe the general issues of representation.	12
	b)	Mention the names of various layers used to design stick diagram of nmos circuit.	8
6.	a)	What do you mean by VLSI design? Discuss the characteristics of VLSI design.	12
	b)	Write a note on branching factor.	8
7.	a)	What do you mean by hierarchy? Describe in detail the geometrical design rule checking.	12
	b)	Describe in brief the issues of connectivity.	8



M.Sc. (Part – II) (Semester – IV) Examination, 2015 ELECTRONICS (New) (CGPA)

Day and Date: Thursday, 16-4-2015 Time: 3.00 p.m. to 6.00 p.m. Instructions: 1) Answer five questions. 2) Question 1 and 2 are compulsory. 3) Attempt any three from Q. 3 to Q. 7. 4) Figures to the right indicate full marks. 1. A) Choose correct answer: 1) band is the IEEE microwave frequency band designation for frequency range 4.000 GHz to 8.000 GHz. A) L B) S C) C D) X 2) A circularly polarized wave has dB ellipticity since E _{max} = E _{min} . A) 0 B) 20 C) 30 D) 10 3) The distance between two successive minima on standing-wave pattern in lossless line is A) λ/4 B) λ C) 2λ D) λ/2 4) In transmission-line problems impedance matching means simply terminating the line in impedance. A) short circuit B) its characteristic C) any D) lowest 5) TEDs A) operate with either junctions or gates B) are bulk devices having no junctions or gates	Pap	er – XIII : N	Microwave Dev	vices, Antennas	and Measurements	
2) Question 1 and 2 are compulsory. 3) Attempt any three from Q. 3 to Q. 7. 4) Figures to the right indicate full marks. 1. A) Choose correct answer: 1) band is the IEEE microwave frequency band designation for frequency range 4.000 GHz to 8.000 GHz. A) L B) S C) C D) X 2) A circularly polarized wave has dB ellipticity since E_max = E_min. A) 0 B) 20 C) 30 D) 10 3) The distance between two successive minima on standing-wave pattern in lossless line is A) \(\lambda / 4 \) B) \(\lambda \) C) 2\(\lambda \) D) \(\lambda / 2 \) 4) In transmission-line problems impedance matching means simply terminating the line in impedance. A) short circuit B) its characteristic C) any D) lowest 5) TEDs A) operate with either junctions or gates	-				Total Marks	: 70
1)band is the IEEE microwave frequency band designation for frequency range 4.000 GHz to 8.000 GHz. A) L B) S C) C D) X 2) A circularly polarized wave hasdB ellipticity since E _{max} = E _{min} . A) 0 B) 20 C) 30 D) 10 3) The distance between two successive minima on standing-wave pattern in lossless line is A) λ/4 B) λ C) 2λ D) λ/2 4) In transmission-line problems impedance matching means simply terminating the line in impedance. A) short circuit B) its characteristic C) any D) lowest 5) TEDs A) operate with either junctions or gates	Ins	2	?) Question 1 and B) Attempt any th	l 2 are compulsor y n ree from Q. 3 to Q	. 7 .	
for frequency range 4.000 GHz to 8.000 GHz. A) L B) S C) C D) X 2) A circularly polarized wave has dB ellipticity since E _{max} = E _{min} . A) 0 B) 20 C) 30 D) 10 3) The distance between two successive minima on standing-wave pattern in lossless line is A) λ/4 B) λ C) 2λ D) λ/2 4) In transmission-line problems impedance matching means simply terminating the line in impedance. A) short circuit B) its characteristic C) any D) lowest 5) TEDs A) operate with either junctions or gates	1. A) Ch	noose correct	answer:			8
 2) A circularly polarized wave has	1)	for frequenc	band is the II by range 4.000 GF	EEE microwave fre Hz to 8.000 GHz.	quency band designation	
 E_{max} = E_{min}. A) 0 B) 20 C) 30 D) 10 3) The distance between two successive minima on standing-wave pattern in lossless line is		A) L	B) S	C) C	D) X	
 3) The distance between two successive minima on standing-wave pattern in lossless line is	2)		ı.			!
in lossless line is A) λ/4 B) λ C) 2λ D) λ/2 4) In transmission-line problems impedance matching means simply terminating the line in impedance. A) short circuit B) its characteristic C) any D) lowest 5) TEDs A) operate with either junctions or gates		A) 0	B) 20	C) 30	D) 10	
 4) In transmission-line problems impedance matching means simply terminating the line in impedance. A) short circuit B) its characteristic C) any D) lowest 5) TEDs A) operate with either junctions or gates 	3)				on standing-wave pattern	l
terminating the line in impedance. A) short circuit B) its characteristic C) any D) lowest 5) TEDs A) operate with either junctions or gates		A) λ/4	Β) λ	C) 2λ	D) λ/2	
C) any D) lowest 5) TEDs A) operate with either junctions or gates	4)			•	=	
5) TEDs A) operate with either junctions or gates		A) short cir	cuit	B) its chara	cteristic	
A) operate with either junctions or gates		C) any		D) lowest		
· · ·	5)	TEDs				
B) are bulk devices having no junctions or gates		A) operate	with either junction	ons or gates		
b) are balk devices having he janotions of gates		B) are bulk	devices having n	o junctions or gate	es	
C) are fabricated from compound semiconductors		C) are fabri	cated from comp	ound semiconduct	ors	
D) both B) and C)		D) both B)	and C)			

10

6) Well-designed directional couplers have a directivity of A) 1 B) zero C) only 30-35 dB D) infinity 7) If a rectangular waveguide carrying a dominant mode is flared out in the plane of magnetic field lines, it is called an _____ horn. A) E-plane sectoral B) H-plane sectoral C) Pyramidal D) Pyramidal exponential 8) Bolometer or the detector sensitivity is _____ A) a measure of bridge unbalance B) slope of the static curve of dc resistance plotted against power for the detector C) usually expressed in ohms pre milliwatt

B) State true or false:

D) both B) and C)

- 1) In TEM wave electric and magnetic fields are perpendicular to each other and both lie in a plane transverse to the direction of propagation.
- 2) For lossless transmission line, $R = G = \infty$.
- 3) The dominant mode in a particular guide is the mode having the lowest cutoff wavelength.
- 4) Slow-wave structures are special circuits that are used in microwave tubes to reduce the wave velocity in a certain direction.
- 5) In Cassegrain antenna system the main dish is paraboloid while the subdish is hyperboloid.
- 6) In waveguide thermistor mount, the thermistor is usually placed near the side wall of the waveguide where the electric field is minimum.

2. A) Write short answers (Attempt two):

- Explain briefly the classification of magnetrons.
- 2) Explain the method of excitation of TE₁₀ mode in rectangular waveguide.
- 3) Explain the double minimum method of measurement of VSWR.
- B) Explain the effect of dc bias on the current sensitivity of the crystal rectifier. 4



3.	a)	Discuss the transmission and reflection of electromagnetic wave at the boundary between to ideal dielectrics for oblique incidence.	8
	b)	Explain the displacement current concept.	6
4.	a)	What do you understand by standing wave and standing-wave ratio? Explain briefly the relationship between reflection coefficient and standing-wave ratio.	8
	b)	A transmission line has a characteristic impedance of 50 + j0.05 Ω and is terminated in a load impedance of 75 – j10.25 Ω . Calculate the reflection coefficient and the standing wave ratio.	6
5.	a)	Draw a schematic diagram of a reflex klystron. Explain the process of velocity modulation in this tube.	8
	b)	Explain the three-valley-model energy level for InP diode.	6
6.	a)	With a schematic diagram explain the characteristics of magic tee.	8
	b)	An air-filled rectangular waveguide of inside dimensions 2.286×1.016 cm operates in the dominant mode. Find the cutoff frequency. Determine the	•
		phase velocity of the wave in the guide at a frequency of 9.0 GHz.	6
7.	a)	With schematic diagrams, explain briefly the probes which are extensively used in the standing-wave detector.	8
	b)	Explain various types of feed arrangements for microstrip patch antenna.	6



Seat	
No.	

M.Sc. (Part - II) (Semester - IV) Examination, 2015

	El (Networking a	LECTRONICS nd Data Comr	-	-	aper – XIV)	
•	Date: Saturday, 18-				Max. Marks :	70
	3) Atte		e co rom	Q. 3 to Q. 7.	rs.	
1. A) Ch	oose correct answ	er:				8
1)	The IEEE 802.11	specifications cov	ers/	the	layers.	
	a) Physical	b) Data Link	c)	Network	d) Both a) and b)	
2)	The L2CAP provid	es				
	a) Multiplexing		b)	Segmentation	n and reassembly	
	c) QoS		d)	All of these		
3)	In line e		ue t	he transition a	t the middle of the bit	
	a) Manchester		b)	Differential M	anchester	
	c) Both a) and b)		d)	None of these	Э	
4)	Thecontrol.	_ channels of AD	SL	are used for d	ownstream data and	
	a) 225	b) 5	c)	25	d) 1	
5)	The Bluetooth tech Hz bandwidth eacl	• •		number of cha	annels of	
	a) 79,4K	b) 79, 1M	c)	256, 1M	d) 256, 4K	



		6)	In IPv4 addressing	g the	e /n defines th	ne				
			a) Addressing	b)	Destination	c)	Mask	d)	Source	
		7)	The ATM is a		relay prot	occ	l.			
			a) Cell	b)	Bit	c)	Byte	d)	Point	
		8)	The routing table n	nay	be1	able	Э.			
			a) Dynamic			b)	Static			
			c) Dynamic or Sta	atic		d)	None of thes	е		
	B)		ate True or False : The jitter refers to	the	variation in t	he r	oacket arrival	time	<u>.</u>	6
		,	The 10Base2 is a			•			•	
		,	The BSS with an A					work	ζ.	
		•	The TDD-TDMA is							
		•	The RG-58 is used							
		6)	In ADSL the chan	nel i	1 is reserved	for v	oice commu	nica	tion.	
2	A)	Att	tempt two :							10
	, ,		Write a note on tra	nsn	nission impai	rme	nt.			.0
		,	Write a note on un		•					
		•	Explain DNS in the	_						
	B)	,	scuss the Bluetooth							4
3.	A)	Ex	plain in detail OSI r	nod	lel.					9
	,		rite a note on virtua			rk.				5
4.	A)	Ex	plain in detail DSL.							9
	,		rite a note on conge	estic	on control.					5
5	۸۱	Dia	scuss in detail ATM	1						9
J.	,		plain the domain n		e svetem					5 5
	ŕ				-					
6.	,		scuss in detail addr		•					9
	B)	Wı	rite a note on multic	ast	routing proto	col.				5
7.	A)	Ex	plain in detail IPv4	add	Iressing.					9
	B)	Wı	rite a note on conne	ectio	on devices.					5



Seat	
No.	

	F	ELECTRO	n. – IV) Examina ONICS (New) (Co noelectronics (E	GPA)	
•		esday, 21-4-2015 6.00 p.m.		M	lax. Marks : 70
Instru		,	re compulsory . e questions out of (r ight indicate full m		
,	The mol	e correct alternative ecular beam epita dimensional ele	ky technique is impo	ortant particularly	8 in forming
	a) 3	b) 2	c) 1	d) none of	these
2)	a) non-b) unifoc) non-	uniform	ade from the same i	material with	doping.
3)	The	dimensional e	lectron gas is quant	um well.	
	a) one	b)two	c) three	d) none of	these
4)	nanome	cept of SET is bas etric structures. b) 2	ed on the behaviou c) 1	r of di	
5)	a) low-rb) polyrc) both	are organic se molecular weight m mers a) and b) e of these			D.T.O.



		6)	The barrier height of a potential electrons is	al square well for holes is and for	
			a) 0.2 eV, 0.4 eV	b) 0.4 eV, 0.2 eV	
			c) 1.4 eV, 0.4 eV	d) 0.2 eV, 1.4 eV	
		7)	The heterojunctions are based	d on compounds.	
			a) III – V	b) IV – V	
			c) III – IV	d) all of these	
		8)	The OLE 19 does not require	es a	
			a) backlight	b) filter	
			c) both backlight and filter	d) none of these	
	B)	Sta	ate true or false :		6
		1)	The quantum wire is effective	ly two dimensional system.	
		2)	The electron energies in the finite well are do not differ too	quantum well obtained for infinite well and much.	
		3)	The Government heterojunctions between Si and Ge.	have minimum lattice constant difference	
		4)	The Multiple Quantum Wel quantum well.	Is (MQW) are formed by several single	
		5)	OLEO's is an electroluming conductors of different work for	nescent organic material between two unctions.	
		6)	The transistor based on hot e	lectrons is called hot electron transistor.	
2.	A)	At	tempt any two :		10
		1)	Explain the limitations of conv	rentional microelectronics.	
		2)	Explain the multiple quantum	well.	
		3)	Explain the concept of superla	attice.	
	B)	Wı	rite a note on organic semicono	ductor.	4
3.			plain in detail fabrication meth		8
J .					
	B)	ĽΧ	plain square quantum well of t	пе шпие аертп.	6



Seat	
No.	

M.Sc. (Part – II) (Semester – IV) (New) Examination, 2015 ELECTRONICS (CGPA) (Elective – III) Paper – XV : Optical Fiber Communication

Day and	Date: T	uesday, 21-4-2015	Max.Marks: 70
- . ~			

Time: 3.00 p.m. to 6.00 p.m.

Instructions: 1) Answer five questions.

- 2) Question 1 and 2 are compulsory.
- 3) Attempt any three from Q. 3 to Q. 7.
- 4) Figures to the right indicate full marks.

1.	A)	Choose correct alternatives:
----	----	------------------------------

8

- 1) In case of stimulated emission, the emitted light depicts
 - a) Deviation in the frequency
 - b) Deviation in amplitude
 - c) Matching of frequency with injected light
 - d) None of these
- 2) _____ is used as front-end amplifier for an optical receiver.
 - a) Pre-amplifier

b) Post amplifier

c) In-line amplifier

- d) SOA
- 3) The critical angle of incidence is given by ϕ_{c} =

a)
$$\frac{n_2}{n_1}$$

b)
$$\sin \frac{n_2}{n_1}$$

c)
$$\frac{n_2 - n_1}{n_2}$$

d)
$$\sin^{-1}\left(\frac{n_2}{n_1}\right)$$

- 4) In _____ optical fiber the refractive index changes gradually.
 - a) Step index

b) Graded index

c) Multi core

d) Multi mode step index

2) Write a note on optical spectral band.

B) What do you mean by numerical aperture?

3) Discuss the sources of error during optical fiber communication.

4

A) What do you mean by step and graded index optical fiber ? With suitable block diagram, describe optical receiver system.B) Describe semiconductor optical amplifier.	10 4
A) Discuss the basic principle of optical amplifier. With suitable diagram explain an architecture of EDFA.B) What is optical dispersion ?	10 4
A) With suitable block diagram describe the optical fiber communication system. B) Write a note on optical transmitter.	10 4
A) What do you mean by WDM? Describe the components of WDM. B) Discuss the advantages of dense WDM.	10 4
A) What do you mean by performance measurement parameters? Describe the methods of power and attenuation measurement.B) Write a note on polarization of light.	10 4



Seat	
No.	

M.Sc. – II (Semester – IV) Examination, 2015 ELECTRONICS (New CGPA) (Elective – IV) (Paper – XVI) Mechatronics and Industrial Automation

Mechatronics a	and Industrial Automation
Day and Date : Thursday, 23-4-2015 Time : 3.00 p.m. to 6.00 p.m.	Max. Marks : 70
•	hree from Q. 3 to Q. 7. e right indicates full marks.
1. A) Fill in the blanks:	8
1) The PLC	_ function is also called as DRUM controller.
a) Sequencer	b) Master control
c) Timer	d) Counter
Normally carried out some kind of a	contact : When this contact closes, the function ction.
a) Open	b) Close
c) Both a) and b)	d) None of these
3) In subtraction, when the re	esult is, the coil turns ON.
a) Positive	b) Negative
c) One	d) Zero
4) Most of PLCs operates on	
a) $+ 5, -5$	b) + 5, Gnd
c) $+5$, -5 and GND	d) +5, GND
5) Modular design is one of the	ne advantage of
a) CCS	b) DCS
c) RTU	d) PLC
6)is sta	nds for output group register.
a) OG	b) IG
c) HR	d) RTU



		7) A single input timer is called a	timer.	
		a) Retentive	b) Nonretentive	
		c) Both a) and b)	d) None of these	
		8) In general PLC have	_ number of input and outputs.	
		a) Same	b) Different	
		c) Only b)	d) None of these	
	B) 3	State true or false :		6
		1) MMI stands for man machin interfac	e.	
		2) 00:01::02 is addressing format of	PLC.	
		3) Output of output logic of I/O module	is connected to the CPU.	
		4) HR stands for Input Register.		
		5) A node is a connection point for two	or more devices.	
		6) RTU stands for Remote Temperatur	e Unit.	
2.	A) :	Solve any two :		10
		1) Write note on DCS communication.		
		2) Explain applications of mechatronic	system.	
		3) Write note on PLC processor.		
	B) (Compare monolithic and Distributed SC	ADA system.	4
3.	A)	Explain arithmetic functions of PLC in de	etail.	8
	B)	Explain design process of mechatronic	system.	6
4.	A) \	Write note on architecture of PLC.		8
	B)	Explain PLC selection in detail.		6
5.	A)	Explain in detail I/O module and their ch	aracteristics.	8
	B) \	Write note on mod bus.		6
6.	A) \	Write note on timer and counter of PLC.		8
	B) \	Write note on sequencer function.		6
7.	A)	Explain concept of industrial automation		8
	В) \	Write note on display units of DCS.		6



Seat	
No.	

	M.Sc. (Part – II) per – XVI : Mix	ELECTRON	ICS (CGPA)	·	
Day and D	Date : Thursday, 23	3-4-2015		T	otal Marks : 70
Time: 3.0	0 p.m. to 6.00 p.m	l.			
Ins	3) Att	estion 1 and 2 at three	ions. are compulsory . e from Q. 3 to Q. 7 a t indicate full ma		
1. a) Ch	noose correct alter	natives :			8
1)	The Variable Clo	ck VC2 is derive	ed from		
	a) VC1		b) SYSCLK×2	2	
	c) SYSCLK×1		d) CPUCLK		
2)	The PSoC1 devi programmable di		s comprises an a	array of	
	a) 12	b) 16	c) 24	d) 4	
3)	In mixed signal ba	sed SoC design	, the computing co	ore performs	the task of
	a) execution of fi	rmware only			
	b) execution of A	PI routine only			
	c) synchronization	on of all on-chip	resources		
	d) none of these				
4)	To establish seri programmable di				input of
	a) data	b) auxiliary	c) interrupt	d) none	of these

2.

3.



	5)	The input impedance	ce of programma	able gain amplifier	of PSoC devices is	
		a) very low	b) high	c) ultra high	d) all of these	
	6)	Which of the following to drive the active s	•	•	stant current source	
		a) IDAC	b) VDAC	c) Vdd	d) TIA	
	7)	In switched capaci	tor technique the	e two clock should	lbe	
		a) out of phase		b) in phase		
		c) of phase differen	nce of 90°	d) none of these		
	8)	The PSoC devices per pin.	are having	mA currer	nt sourcing capacity	
		a) 25 mA	b) 10 mA	c) 20 mA	d) 15 mA	
b)	Sta	ate true or false :				6
	1)	In case of Cypress	PSoC 3, the 805	51 core is used for	processing.	
	2)	Decimator block of frequency.	f delta sigma Al	DC is used to inc	rease the sampling	
	3)	As per the hardware interfaced with glob	•	•	umbered buses are	
	4)	SC analog block ca	ın be programme	ed as an integrator		
	5)	The delta sigma AD	OC of PSoC dem	onstrate the use o	f oversampling.	
	6)	If VDD = 5V, then of voltage for analog of	-		ption, the reference	
A)	Att	tempt any two :				10
	1)	With block diagram	, describe the ar	n architecture of M	I8C core of PSoC1	
	2)	Write a note on sys	stem bus.			
	3)	What do you mean	by clocking sub	system of PSoC?		
B)	Wı	rite a note on Interru	pt subsystem.			4
A)		escribe the principle on the contract of SC programm	• .		undamental building	7
B)		nat do you mean by nctional building bloo		analog block? De	escribe in detail the	7



4.	A)	With the suitable block diagram describe an array of programmable digital blocks. Discuss fundamental architecture of programmable digital block.	7
	B)	Give the configuration LCD Module of PSoC device.	7
5.	A)	What do you mean by Delta Sigma modulation? With suitable diagram describe an architecture of Delta Sigma ADC of PSoC device.	7
	B)	Describe an interfacing of PIR sensor to PSoC device.	7
6.	A)	With suitable block diagram describe the design of mixed signal based system on chip for measurement of temperature of the environment.	7
	B)	Describe in detail the configuration of IDAC of the PSoC devices.	7
7.	A)	What do you mean by mixed signal based SoC design? Discuss the characteristics programmable system on chip.	7
	B)	Describe in detail programmable SPI and UART block of PSoC device.	7



Seat	
No.	

M.Sc. (Part - II) (Semester - IV) (New) Examination, 2015

		ELECTRONICS ireless Sensor	(CGPA) Network (Electiv	e – IV)
•	ate : Thursday, 23-0) p.m. to 6.00 p.m.	4-15		Max. Marks : 70
Instru	3) Attempt	and 2 are comp	Q. No. 3 to Q. No. 7 .	
1. A) Cho	oose correct alterna	tive :		8
,	Wireless Sensor Ne	twork.	en adopted by the Zigk	
	,	•	c) 802.11	•
•	In 2.4 GHz band configuration.		channels are availa	able for WSN
	a) 16	b) 4	c) 10	d) None of these
ŕ	The Wireless Senson a) End devices b) Coordinators c) End devices and d) Routers		collaborative network	(ing of
ŕ	Physical layer of the a) Frequency of corb) Address of the neconstruction Packeting of data d) Networking protes	mmunication and odes a	nature of modulation	



		5)	The zigbee devices, consist of or	chip	
			a) Transreceiver model		
			b) Microcontroller core		
			c) Microcontroller core along with	n communication interfaces	
			d) None of these		
		6)	In Hierarchical protocols the end	devices communicate with the	
			a) end device	b) cluster head	
			c) coordinator	d) base station	
		7)	FFD stands for	device.	
			a) False Function	b) Full Function	
			c) Four Functions	d) None of these	
		8)	C1WSN is invariably mesh bas connectivity between wireless se		
			a) Single hop	b) Multihop	
			c) Random hop	d) None of these	
	B)	Sta	ate true or false .		6
		1)	SPIN is data centric negotiation b	ased family of protocol.	
		2)	PEGASIS is the best example of	nierarchical networking.	
		3)	The wireless sensor nodes are no	ot autonomous devices.	
		4)	Zigbee devices can be configured	d only in unicast mode.	
		5)	For programming of the Zigbee de	evices the XCTU is recommended.	
				assembling and disassembling of the	
2.	A)	Att	tempt any two .		10
	,		With the block diagram describe	an architecture of WSN.	
		•	What do you mean by networking		
			What do you mean by network se		
	B)	•	ention applications of Wireless Ser	•	4
3.	A)	De	escribe block diagram and pin desc	cription of the Zigbee device.	10
	•		rite note on LEACH protocol.	. •	4
	-,				

4.	A)	Describe in detail, the standards IEEE 802.15.4. Explain network layers of the WSN.	10
	B)	Write a note on attacks in the WSN.	4
5.	A)	With suitable diagram explain the design of sensor node for WSN using AVR microcontroller for agricultural application.	10
	B)	Explain serial communication UART in Zigbee technology.	4
6.	,	Describe operating modes of Zigbee devices. What do you mean by energy management in WSN?	10
7.	,	What do you mean by hierarchical architecture of the WSN? Describe in detail the function of PEGASIS protocol.	10
	B)	Write a note on C2WSN.	4



Seat	
No.	

M.Sc. (Part – II) (Semester – IV) Examination, 2015 ELECTRONICS (Old)

Paper - XIII: Microwave Devices. Antennas and Measurements

· up	,	miorowave Be	rioco, Ainomi	ao ana moaoaromo	110
-	Date : Thurs 00 p.m. to 6.	day, 16-4-2015 00 p.m.		Total Ma	rks : 100
Ins	structions :	, .	nd 2 are compuls three from Q. 3 to e right indicate m	Q. 7 .	
1. a) Cl	noose corre	ct answer.			8
1)	The reflex	klystron is a	cavity I	dystron oscillator.	
,	A) three	•	C) single		
2)	approxima A) 300 Hz	es are electromag tely to 1000 GHz to 1MHz	– B) 300 kHz t		m
3)		rectional coupler s st possible		directivity.	
4)	The SMC is	sa	ohm connector	hat is smaller than the S	MA.
,	A) 100		– C) 150		
5)	A) usuallyB) is the single for the cC) both A)	detector	ns per milliwatt curve of d-c resis	 tance plotted against po	ower
	D) measur	e of the bridge un	balance		



	6) For a rectangular-cavity resonator having a > b < d, the dominant mode is mode.			
		A) TM ₁₀₁ B) TE ₁₁₀ C) TM ₁₀₀ D) TE ₁₀₁		
	7)	In double minimum method of measurement of high VSWR, the probe is		
		 A) always located in the region of low impedance B) located in the region of high impedance C) located either in the region of low or high impedance D) strictly located in the region of high impedance 		
	8)	The horn is usually used as a standard primary gain antenna. A) sectoral H-plane B) sectoral E-plane C) pyramidal D) sectoral H-plane or sectoral E-plane		
b)	Fil	l in the blanks :	6	
The dominant mode in a particular guide is the mode having the cutoff frequency. (lowest/highest)				
	2)	The application of the ac network theory requires that all dimensions of the circuit elements be much than the wavelength. (smaller/larger)		
	3)	The range of microwave power 10 mW to 1 watt is referred to aslevel power. (low/medium)		
	4)	The bandwidth of a square or circular patch antenna with decreasing substrate thickness h. (decreases/increases)		
	5)	A flat line is (resonant/nonresonant)		
	6)	Magnetron oscillators are ordinarily operated in the mode. (π / 2π)		
c)	Sta	ate true or false :	6	
	1)	The presence of slot in the transmission line changes the boundary conditions.		
	2)	In two-cavity klystron amplifier, the cavity close to the cathode is known as catcher cavity.		
	3)	Since another antenna is required to excite a reflector antenna, it is usually called a secondary antenna.		



- 4) In transmission-line problems matching means simply terminating the line in short circuit impedance.
- 5) In Rotary-vane attenuator, the input transition converts the ${\rm TE}_{10}$ wave into a vertically polarized ${\rm TE}_{11}$ wave in circular guide.
- 6) To communicate efficiently between two points, it is important that the transmitted signal be sharply focused and aimed at the receiving antenna.

2.	Wr	rite short answers (any four) :	2 0
	a)	With rms-phasor explain a liner polarized wave.	
	b)	Explain any two applications of a magic tee.	
	c)	What are the scales on the Smith Chart? Explain briefly.	
	d)	With schematic diagram explain the construction of Cassegrain antenna.	
	e)	Explain the fundamental difference between transistors and TEDs.	
3.	a)	Obtain the equation for line impedance at the sending end of the line.	12
	b)	Explain the boundary conditions for electric and magnetic fields.	8
4.	a)	Explain the most obvious and most essential requisite of thermistor mount. What do you understand by "O-O" and "S-S" mounts?	12
	b)	Describe Maxwell's equations for EM waves.	8
5.	a)	Explain two-valley model of electron energy versus wave number for n-type GaAs.	12
	b)	What are various types of horn antennas? Explain the construction of H-plane and E-plane sectoral horns.	e 8
6.	a)	Explain the construction and working of the rotary-vane attenuator.	12
	b)	What do you mean by transmission lines? Explain transmission line equations.	8
7.	a)	Explain the use of a crystal detector as heterodyne converter in detection of microwave power.	12
	b)	Explain two kinds of probes which are extensively used in standing-wave detector.	8



Seat	
No.	

M.Sc. (Semester – IV) Examination, 2015 ELECTRONICS (Old) Paper – XIV : Networking and Data Communication

rapei – XIV. Netwoi	king and Data Communication
Day and Date: Saturday, 18-4-2015 Time: 3.00 p.m. to 6.00 p.m.	Max. Marks: 100
3) Attempt an	y five questions. . 2 are compulsory . y three questions from Q. 3 to Q. 7 . the right indicates full marks.
1. A) Select correct alternative :	8
1) Bluetooth is an net	twork.
a) infrastructured	b) ad-hoc
c) both a) and b)	d) none of these
2) The differential Manchester	combiner the ideas of
a) RZ and NRZ – I	b) RZ and NRZ – L
c) NRZ and NRZ – I	d) NRZ and ZRZ – L
3) Asynchronous Transfer Mo	de (ATM) is the relay protocol.
a) bit	b) cell
c) byte	d) 2 byte
4) In SONET the duration of S	TS – 3 frame is
a) 125 μs	b) 375 μs
c) 80 µs	d) None of these
5) Thecontrol is	s achieved by adding trailer at the end of frame.
a) flow	b) error
c) access	d) all of these
6) The presentation layer is re	esponsible for
a) translation	b) compression
c) encryption	d) all of these
	P.T.O.

2. Attempt any four:

20

- 1) Explain bridge.
- 2) Write a note on transmission impairment.
- 3) Explain domain name space.
- 4) Write note on circuit switched network.
- 5) Discuss architecture of bluetooth.

	-3-	SLR-SP - 267
3.	A) Explain OSI model in detail.	12
	B) Explain ZPv4.	8
4.	A) Explain in detail ATM.	12
	B) Write a note on DSL.	8
5.	A) Explain in detail data link layer protocol.	12
	B) Write a note on WWW and Electronic mail.	8
6.	A) What do you mean cryptography?	12
	B) Write a note on ZP security.	8
7.	A) Explain in detail UDP and TCP.	12
	B) Explain DNS in the internet.	8

SLR-SP - 268



Seat	
No.	

M.Sc. (Part - II) (Semester - IV) Examination, 2015

	(Paper – XV) :	ÉLECTRON ARM Microcor	• •	stem Design	
Day and	Date : Tuesday, 21	l-4-2015		Max. Marks:	: 100
Time : 3.0	00 p.m. to 6.00 p.r	n.			
Insti	iii) Atte	empt five question estion 1 and 2 are c empt any three fro ures to the right in	compulsory. om Q. 3 to Q. 7 .	s.	
1. A) S	elect the correct a	Iternatives :			8
1) When subroutine	e is called, process	sor stores return a	address in	
a) Program Counter		nter	b) Stack Poi	nter	
	c) Link Register		d) None of th	ese	
2)ar	e banked registers			
	a) r ₁₄ – r ₁₇	b) r ₇ – r ₁₃	c) $r_0 - r_7$	d) r ₈ - r ₁₄	
3) ARM7 has	stage pipeline.			
	a) 3	b) 5	c) 7	d) 9	
4) LPC 2378 has _	timers/	counts.		
	a) 1	b) 2	c) 3	d) 4	
5	b) ARM Micropr	ontroller Bus Archit rocessor Bus Archi crocontroller Bus A	tecture		
6)regis	ster is accessible in	n all processor mo	odes.	
	a) Link register		b) Banked re		
	c) Unbanked reg	gister	d) Current pr	ogram status register	•

	7)	ARM supportsty	pes exception.		
		a) 1 b) 2	c) 4	d) 5	
	8)	The cache is placed between			
		a) Flash memory and registers	5.		
		b) Main memory and core			
		c) Peripherals			
		d) None of these			
B)	Fill	ll in the blanks :			6
	1)	Jazellel executes	bit instructions.		
		(8, 16)			
	2)	LPC 2378 has SRAM	M for etternet interfac	e.	
		(16 KB, 32 KB)			
	3)	are unbanked regis	ters.		
		$(r_{11} - r_{13}, r_0 - r_7)$			
	4)	ARM processor can operated in	nmc	odes.	
		(9, 7)			
	5)	register is the proo	gram counter.		
		(r ₁₅ , r ₁₃)			
	6)	LPC 2378 hasflas	sh memory.		
		(32 KB, 512 KB)			
C)	Sta	ate True or False :			6
	1)	r ₁₄ register is the link register.			
	2)	Thumb instructions set execute	es 16 bit instructions	,	
	3)	LPC 2378 has four Timers/Cou	nters.		
	4)	Banked register is accessible i	n all processor mode	es.	
	5)	To improve the code density A	RM uses Thumb inst	ruction set.	

6) ARM core is 64 bit processor.



2.	Wı	rite short answers (any four) :	20
	a)	Compare ARM, Jazzele and Thumb instruction set.	
	b)	With suitable block diagram describe AMBA Bus architecture.	
	c)	What do you mean by TDMI?	
	d)	What do you mean by mulitply and accumulate instruction?	
	e)	Write a note on memory organization of LPC 2378.	
3.	a)	Explain with suitable block diagram the architecture of LPC 2378.	12
	b)	Describe the pipelining of ARM microcontroller.	8
4.	a)	What do you mean by ARM instruction set architecture? Give the classification of instruction set.	12
	b)	Describe modes of ARM processor.	8
5.	a)	Describe the designing of ARM microcontroller based an embedded system to measure humidity.	12
	b)	Describe the interfacing of optocouple to LPC 2378.	8
6.	a)	Mention the salient features of LPC 2378 and describe register section of ARM core.	12
	b)	Write a note on barrel shiffer.	8
7.	a)	Describe the ARM core philosophy and explain AW section in detail.	12
	b)	Write a note on interrupts/exceptions.	8



Seat	
No.	

M.Sc. – II (Semester – IV) Examination, 2015 ELECTRONICS (Old) Paper – XV : PRO ASIC System Design

	га	pei – XV. Fii	O AGIC Gysi	leni Design	
_	Date : Tuesda 00 p.m. to 6.00	•			Max. Marks: 100
Ins	2 3	() Solve any five () Q. 1 and Q. 2 a () Solve any thr () Figures to the	are compulsor ee questions fr	om Q. 3 to Q. 1	7.
1. A) Se	elect correct a	nswer:			8
1)	ASSP is syn	onym of			
	a) Application	n Specific Stand	ard Point		
	b) Application	n Specific Standa	ard Product		
	c) Application	n Specific Stand	ard Pin		
	d) Application	n Specific Stand	ard Positive		
2)		Gate Array is als			
	-	ree gate array	_	-	
	c) SOG arra		d) All of the		
3)		mable ASIC inter		base	ed metalization.
	a) gold		b) silver		
	c) aluminum		d) all of thes		_
4)		A the programn o the routing net		nection points	s connects the
	a) logic elem	ent	b) CLB		
	c) macro		d) none of th	nese	
5)	The thermal	resistance $\mathcal{O}_{\mathcal{I}_{\ell}}$	for VQFP pac	kage is	°CW ⁻¹ .
	a) 44	b) 68	c) 33	d) 40	
6)	The totem-p same type.	ole output buffer	has	stacked tra	ansistors of the
	a) one	b) two	c) three	d) four	



	7)	The bulk resistance of metal-me	tal antifuse link is	3	
		a) 500 $\mu\Omega$ cm	b) 500 Ω cm		
		c) 500 Ω	d) $500\mathrm{m}\Omega$ cm		
	8)	The CBIC reduces the risk due t	0	standard cell library.	
		a) Pretested	b) Predefined		
		c) Precharacterized	d) All of these		
B)	Fill	l in the blank :			6
	1)	The module ADO is a			
		(datapath/datapath cell)			
	2)	ZN = OAI 22 [A, S, B, NOT (S)] i	is	_2:1 MUX.	
		(inverting/non inverting)			
	3)	ACT-2 and ACT-3 architectures and one of them is equivalent of			
		(O/RS)			
	4)	The AOI family has or less.	number of cells v	vith three index numbers	
		(70/56)			
	5)	All logic cells are predefined and in ASIC.	d possibly all mar	k layers are customized	
		(full custom/semi-custom)			
	6)	The intrinsic parasitic capacita CMOS process.	ince of an antifu	se is appro. 1-2 fF for	
		(1 μm/0.5 μm)			
C)	Sta	ate true or false :			6
	1)	Actel's LVT (1010, 8 channels) h	nas connects to 2	200 antifuse.	
	2)	The 0.5 μm or 1.0 μm technological parameters.	ogy is not used fo	or XC 3000 interconnect	
	3)	The flip-flop with a fast clock to	Q delay is build ι	using inverters with TG.	
	4)	Xilinx CLBs contain both combin	national logic and	flip-flop.	
	5)	FPGA are not ideal for prototypi	ng system or for l	ow-volume production.	
	6)	The microprocessor is ASIC chi	D.		



2.	Solve any four:	20
	1) Explain Shannon's expansion theorem.	
	2) Write a note on library architecture.	
	3) Explain Xilinx I/O blocks.	
	4) Write a note on gate-array based ASIC.	
	5) Explain routing resources.	
3.	A) What do you mean programmable ASIC IO cells?	12
	B) Explain datapath logic cells.	8
4.	A) Explain in detail different types of ASIC.	12
	B) Explain RC delays in antifuse.	8
5.	A) Explain in detail programmable ASIC logic cells from ACTEL.	12
	B) Write a note on pushing bubbles.	8
6.	A) Explain in detail following terms :	12
	1) Cell compilers	
	2) CMOs as resistor.	
	B) Write a note on speed grading.	8
7.	A) Explain in detail issues of ASIC library design.	12
	B) Write a note on Elmores constant.	8



Seat	
No.	

M.Sc. Electronics (Semester – IV) (Old) Examination, 2015 Paper – XVI: INDUSTRIAL CONTROLLERS AND AUTOMATION

		7.01011.7111011
Day and Date : Thursday, 23-4-2015		Total Marks : 100
Time: 3.00 p.m. to 6.00 p.m.		
Instructions: 1) Attempt any five que 2) Q. 1 and Q. 2 are co 3) Attempt any three q 4) Figure to the right in	mpulsory . Juestion from Q. 3 to Q). 4 .
1. A) Select correct alternative.		8
1) Select correct statement for final	I value theorem X (∞)	=
a) $\lim_{z \to 1} [(z^{-1} - 1) X (z)]$	b) $\lim_{z \to 0} [(z^{-1} - 1)]$	1) X (z)]
c) $\lim_{z\to\infty} X(z)$	d) all of these	
2) Z – transform of the δ (n) is =		
a) 1 b) 2	c) 3	d) 4
3) Programmable logic controllers (PLC's) are used for	
a) Producing on-off output voltag	ge	
b) Actuating elements such as e	electric motor, solenoid	d etc.
c) Both a and b		
d) None of these		
4) VDU stands for		
 a) Vertual display unit 	b) Video display u	ınit
c) Vertical display unit	d) None of these	
5) JSP stands for in S	SCADA protocols.	
a) In-System-Programming	b) Inter-Operable	System Project
c) In System Process	d) Both a) and b)	



6)	and source of the		part of Group disp	lay, Graph of output
	a) Group	b) Overview	c) Detail	d) Graphic
7)	A ladder diagram i	s used as a		
	a) PLC programm	ning	b) Storage facilit	у
	c) Communicatio	n facility	d) None of these	
8)	In digital control sy	stemis e	essential when sen	sor output is analog.
	a) Amplifier	b) Clipper	c) Clamper	d) ADC
B) Fil	ll in the blanks.			

1)	Z-transform of $\frac{z}{z-3}$; $ z > 3$ is (3 ^{-k} u(n)/3 ^h u(n))
2)	is used for isolation (Optocupler/OFC)
3)	is not SCADA protocol (Ambabus/Profibus)
4)	is used to program PLC (Programmer/I/O Module)
5)	SCADA system distributes in types. (2/3)

6) _____ display shows simulation of the system (Group/Graphic)

C) State true or false.

6

6

- 1) C language is used for PLC programming.
- 2) ROC stands for Region of convergence.
- 3) $\frac{1}{1+Ts}$ is transfer function of low pass system.
- 4) Modbus is one of the SCADA protocol.
- 5) Digital control system is less noisey system.

6)
$$x(0) = \lim_{z \to \infty} [X(1)]$$
.



2.	Att	empt any four.	20
	1)	Draw and explain centralized control system.	
	2)	Write a note on poles and zeros.	
	3)	Explain Digital Control System.	
	4)	Write a note on Registers of PLC.	
	5)	Explain Remote Terminal Unit (RTU).	
3.	A)	Compair Centralized Control System (CCS) and Distribute Control System in	
		detail.	10
	B)	Explain time and frequency domain system with suitable example.	10
4.	A)	With suitable Example, Explain Z-transform theorems.	10
	B)	Write note on memory and Power Supply unit of PLC's.	10
5.	A)	Draw and Explain Architecture of SCADA system in detail.	10
	B)	Explain timers of PLC with suitable Example.	10
6.	A)	Explain Programming for ON-Off I/O for PLC.	10
	B)	Explain transformation of problem in to W domain.	10
7.	A)	Design ladder diagram for Simple Process Control.	10
	B)	What do you mean by Master Control Relay (MCR)? With suitable example. Explain MCR in detail.	10



Seat	
No.	

ELECTRONICS (Old) Paper – XVI : Wireless Sensor Network			
Day and Date : Thursday, 23-4-2015	Total Marks : 100		
Time : 3.00 p.m. to 6.00 p.m.			
Instructions: 1) Attempt five question 2) Q. 1 and Q. 2 are composite 3) Attempt any three (4) Figures to the right	ompulsory. questions from Q. 3 to Q. 7 .		
1. a) Choose correct alternatives :	8		
 In Qos based routing protocol, the and is maintained. 	balance between of data		
a) Quality, Energy consumption			
b) Power, Quality			
c) Quality, Speed			
d) Quality, Data rate			
Routing is the process of	_ data through path in network traffic.		
a) Sending	b) Checking		
c) Breaking	d) None of these		
3) 802.11 standard is used for			
a) WLAN	b) WPAN		
c) Both a) and b)	d) None of these		
4) For saving battery power Mobile S	,		
a) Transmission mode	b) Receiving mode		
c) Cluster head	d) Sleep mode		



	5) IEEE standard for Zigbee is		
	a) 802.15.4	b) 802.15.5	
	c) 802.15.6	d) 802.15.7	
	6) In flat routingno	de play same role.	
	a) 50%	b) 75%	
	c) 80%	d) all	
	7) In three tiered architecture of	of WSN the upper tier is	
	a) Access point	b) Mobile agent	
	c) Static sensor node	d) None	
	8)standard used in v	wired LAN.	
	a) IEEE 802.3	b) IEEE 802.5	
	c) IEEE 802.16	d) IEEE 802.20	
b)	Fill in the blanks :		6
	1) For saving battery power Mo	obile Station (MS) enter into	
	(sleep mode, receiving mode	e)	
	2) The channel bit rate of GSM	iskbps.	
	(270, 250)		
	3) LEACH is based p	protocol.	
	(cluster, optimal chain)		
	4) Protocol standard of Zigbee	is	
	(IEEE 802.15.1, IEEE 802.1	5.4)	
	5) 802.11 standard used for		
	(WLAN, WPAN)		
	6) SPR stands for		
	(short path routing, sleep pri	imary routing)	
c)	Identify true/false statement :		6
	1) Lower energy node used for	sensing.	
	2) MAC stand for Media Acces	s Control.	
	3) Short path routing is frequer	ntly approximated to straight line routing.	
	4) Network topology changed i	n WSN due to failure of intermediate node.	
	5) IEEE 802.15.4 is protocol sta	andard of Zigbee.	
	6) The primary component of V	VSN is sensor.	



2.	Attempt any four:	20
	a) Write a note on CDMA.	
	b) Write a note on cluster gateway switch routing protocol.	
	c) Explain MAC management in 802.15 wireless PAN.	
	d) Explain sensor network management.	
	e) Write a note on SPR.	
3.	a) Explain schemes of routing in dynamic wireless sensor network.	10
	b) Explain Tiered architecture in sensor network.	10
4.	a) Draw and explain architecture and wireless sensor network.	10
	b) Give the application of wireless sensor network.	10
5.	a) Draw and explain architecture of zigbee module.	10
	b) Explain taxonomy of routing technique in wireless network.	10
6.	a) Explain 802.11 wireless networking protocol.	10
	b) What is energy management? Explain any two types.	10
7.	a) Explain 802.15 wireless networking protocol.	10
	b) Explain security issues of wireless sensor network.	10

SLR-SP - 272



Seat	
No.	

M.Sc. (Part - II) (Semester - IV) Examination, 2015 **ELECTRONICS (Old)** Paper - XV1 : Mixed Signal SoC Design

Day and Date: Thursday, 23-4-2015 Time: 3.00 p.m. to 6.00 p.m. Total Marks: 100

ime: 3.0	o p.m. to 6.00 p.m.		
Ins	tructions : 1) Answer five question 2) Question 1 and 2 are 3) Attempt any three find 4) Figures to the right in	ecompulsory. rom Q. 3 to Q. 7 .	
1. A) Ch	oose correct answer:		8
1)	Mixed signal based SoC comprises	S	
	a) analog block with microcontrolle	er	
	b) digital blocks with microcontroll	er	
	c) both analog and digital blocks w	vith microcontroller core	
	d) only microcontroller		
2)	is the basic char	acteristic of the PSOC devices.	
	a) Integrability	b) Configurability	
	c) Adoptability	d) None of these	
3)	BiCMOS is the combination of		
	a) two CMOS transistors		
	b) two BJT		
	c) BJT and CMOS transistor		
	d) all of these		
4) In case of cypress PSOC1 the analog blocks are arranged array of			
	a) rows	b) columns	
	c) bytes	d) none of these	



In delta-sigma a analog to digital co within		nvertor the input signal should be	
	a) OV to + Vref	b) - Vref to OV	
	c) - Vref to + Vref	d) none of these	
6)	In switched capacitor analog blocks	of PSOC, the resistor is given by	
			
	a) $R = \frac{1}{cfs}$	b) R = c.fs	
	c) $R = \frac{c}{fs}$	d) $R = \frac{1}{fs}$	
7)	In case of cypress PSOC the sinking	g current is	
	a) 10 mA	b) 25 mA	
	c) 5 mA	d) 1 mA	
8)	Variation in the clock frequency due	to temperature variation is called as	
	a) fraguancy modulation	h) alaak littar	
	a) frequency modulation	b) clock Jitter	
D) E::::	c) temperature Jitter	d) none of these	•
,	in the blanks :		6
1)	The crystal frequency for external clo	OCK IS	
- `	[24 MHz, 32.768 KHz]		
2)	The M8C microcontroller is having _	interrupt sources	
_,	[8, 25]		
3)	The PSOC comprises	reference levels for continuous	
	time analog bocks.		
4)	[3, 1]	an A DO 4a	
4)	The decimeter used in $\Delta \cdot \Sigma$ modulat the frequency.	or ADC to converts	
	[down, up]		
5)	Type C switched capacitor block con	sists of analog input.	
ŕ	[1, 2]	- ·	
6)	is the fundamental	stage for CMOS operational amplifier.	
·	[current mirror, pull up]	•	
	-		



	C) State true or false :	6
	 PSOC1 device has global odd and global even digital bus inter co The switch capacitor block is only used to configure the program 	
	gain amplifier.	
	3) The ADC of mixed signal devices has programmable resolution.	
	4) In case of SAR ADC the resolution is equal to $\frac{2^{B}-1}{2}$.	
	5) PSOC1 is having unprogrammable communication interfaces.	
	6) The clock source Vc ₂ is obtained from Vc ₃ .	
2.	2. Attempt any four of the following:	20
	1) Write a note on BiCMOS transistor.	
	2) What do you mean by concept of system on chip?	
	3) What do you mean by clock source of PSOC devices?	
	4) Write a note on switched capacitor summing amplifier.	
	5) Discuss the term reconfigurability.	
3.	 A) What do you mean by mixed signal technology? Describe in detail the architecture of mixed signal based programmable system on chip. 	ne 12
	B) Write a note on system buses.	8
4.	 A) Discuss the principle of switched capacitor. Describe in detail the sw capacitor analog block of PSOC1. 	vitched 12
	B) Write a note on CMOS operational amplifier design.	8
5.	5. A) Describe in detail, the continuous time analog building blocks.	12
	B) Write a note on configuration of programmable gain amplifier.	8
6.	A) What do you mean by delta-sigma modulation? Describe in detail, the delta-sigma ADC.	ne 12
	B) Discuss the impact of circuit non-idealities on ADC performance.	8
7.	 A) Describe in detail the mixed signal based system on chip for tempera measurement. 	ature 12
	B) Write a note on programmable digital timer block.	8